Package ‘spmoran’

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Title Fast Spatial Regression using Moran Eigenvectors

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Description

Functions for estimating spatial varying coefficient models, mixed models, and other spatial regression models for Gaussian and non-Gaussian data. Moran eigenvectors are used to an approximate Gaussian process modeling which is interpretable in terms of the Moran coefficient. The GP is used for modeling the spatial processes in residuals and regression coefficients. For details see Murakami (2021) <arXiv:1703.04467>.

Encoding UTF-8

Imports sp, fields, vegan, Matrix, doParallel, foreach, ggplot2, spdep, rARPACK, RColorBrewer, splines, FNN, methods

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VignetteBuilder R.rsp

NeedsCompilation no

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`besf` *Spatial regression with RE-ESF for very large samples*

Description

Memory-free implementation of RE-ESF-based spatial regression for very large samples. This model estimates residual spatial dependence, constant coefficients, and non-spatially varying coefficients (NVC; coefficients varying with respect to explanatory variable value).

Usage

```
besf( y, x = NULL, nvc = FALSE, nvc_sel = TRUE, coords, s_id = NULL,
      covmodel="exp", enum = 200, method = "reml", penalty = "bic", nvc_num = 5,
      maxiter = 30, bsize = 4000, cl = NULL )
```

Arguments

`y`	Vector of explained variables (N x 1)
`x`	Matrix of explanatory variables (N x K)
`nvc`	If TRUE, NVCs are assumed on x. Otherwise, constant coefficients are assumed. Default is FALSE
`nvc_sel`	If TRUE, type of coefficients (NVC or constant) is selected through a BIC (default) or AIC minimization. If FALSE, NVCs are assumed across x. Alternatively, nvc_sel can be given by column number(s) of x. For example, if nvc_sel = 2, the coefficient on the second explanatory variable in x is NVC and the other coefficients are constants. The Default is TRUE
`coords`	Matrix of spatial point coordinates (N x 2)
`s_id`	Optional. ID specifying groups modeling spatially dependent process (N x 1). If it is specified, group-level spatial process is estimated. It is useful. e.g., for multilevel modeling (s_id is given by the group ID) and panel data modeling (s_id is given by individual location id). Default is NULL

covmodel	Type of kernel to model spatial dependence. The currently available options are "exp" for the exponential kernel, "gau" for the Gaussian kernel, and "sph" for the spherical kernel
enum	Number of Moran eigenvectors to be used for spatial process modeling (scalar). Default is 200
method	Estimation method. Restricted maximum likelihood method ("reml") and maximum likelihood method ("ml") are available. Default is "reml"
penalty	Penalty to select type of coefficients (NVC or constant) to stablize the estimates. The current options are "bic" for the Baysian information criterion-type penalty (N x log(K)) and "aic" for the Akaike information criterion (2K) (see Muller et al., 2013). Default is "bic"
nvc_num	Number of basis functions used to model NVC. An intercept and nvc_num natural spline basis functions are used to model each NVC. Default is 5
maxiter	Maximum number of iterations. Default is 30
bsize	Block/badge size. bsize x bsize elements are iteratively processed during the parallelized computation. Default is 4000
cl	Number of cores used for the parallel computation. If cl = NULL, the number of available cores is detected. Default is NULL

Value

b	Matrix with columns for the estimated coefficients on x, their standard errors, z-values, and p-values (K x 4). Effective if nvc =FALSE
c_vc	Matrix of estimated NVCs on x (N x K). Effective if nvc =TRUE
cse_vc	Matrix of standard errors for the NVCs on x (N x K). Effective if nvc =TRUE
ct_vc	Matrix of t-values for the NVCs on x (N x K). Effective if nvc =TRUE
cp_vc	Matrix of p-values for the NVCs on x (N x K). Effective if nvc =TRUE
s	Vector of estimated variance parameters (2 x 1). The first and the second elements denote the standard error and the Moran's I value of the estimated spatially dependent component, respectively. The Moran's I value is scaled to take a value between 0 (no spatial dependence) and 1 (the maximum possible spatial dependence). Based on Griffith (2003), the scaled Moran'I value is interpretable as follows: 0.25-0.50:weak; 0.50-0.70:moderate; 0.70-0.90:strong; 0.90-1.00:marked
e	Vector whose elements are residual standard error (resid_SE), adjusted conditional R2 (adjR2(cond)), restricted log-likelihood (rlogLik), Akaike information criterion (AIC), and Bayesian information criterion (BIC). When method = "ml", restricted log-likelihood (rlogLik) is replaced with log-likelihood (logLik)
vc	List indicating whether NVC are removed or not during the BIC/AIC minimization. 1 indicates not removed whreas 0 indicates removed
r	Vector of estimated random coefficients on Moran's eigenvectors (L x 1)
sf	Vector of estimated spatial dependent component (N x 1)
pred	Vector of predicted values (N x 1)
resid	Vector of residuals (N x 1)
other	List of other outputs, which are internally used

Author(s)

Daisuke Murakami

References

Griffith, D. A. (2003). Spatial autocorrelation and spatial filtering: gaining understanding through theory and scientific visualization. Springer Science & Business Media.

Murakami, D. and Griffith, D.A. (2015) Random effects specifications in eigenvector spatial filtering: a simulation study. Journal of Geographical Systems, 17 (4), 311-331.

Murakami, D. and Griffith, D.A. (2019) A memory-free spatial additive mixed modeling for big spatial data. Japan Journal of Statistics and Data Science. DOI:10.1007/s42081-019-00063-x.

See Also

resf

Examples

```
require(spdep)
data(boston)
y <- boston.c[, "CMEDV" ]
x <- boston.c[,c("CRIM","ZN","INDUS", "CHAS", "NOX","RM", "AGE",
                       "DIS" ,"RAD", "TAX", "PTRATIO", "B", "LSTAT")]
xgroup  <- boston.c[,"TOWN"]
coords  <- boston.c[,c("LON", "LAT")]

######## Regression considering spatially dependent residuals
#res   <- besf(y = y, x = x, coords=coords)
#res

######## Regression considering spatially dependent residuals and NVC
######## (coefficients or NVC is selected)
#res2  <- besf(y = y, x = x, coords=coords, nvc = TRUE)

######## Regression considering spatially dependent residuals and NVC
######## (all the coefficients are NVCs)
#res3  <- besf(y = y, x = x, coords=coords, nvc = TRUE, nvc_sel=FALSE)
```

---

besf_vc *Spatially and non-spatially varying coefficient (SNVC) modeling for very large samples*

Description

Memory-free implementation of SNVC modeling for very large samples. The model estimates residual spatial dependence, constant coefficients, spatially varying coefficients (SVCs), non-spatially varying coefficients (NVC; coefficients varying with respect to explanatory variable value), and SNVC (= SVC + NVC). Type of coefficients can be selected through BIC/AIC minimization. By default, it estimates a SVC model.

Note: SNVCs can be mapped just like SVCs. Unlike SVC models, SNVC model is robust against spurious correlation (multicollinearity), so, stable (see Murakami and Griffith, 2020).

Usage

```
besf_vc( y, x, xconst = NULL, coords, s_id = NULL, x_nvc = FALSE, xconst_nvc = FALSE,
         x_sel = TRUE, x_nvc_sel = TRUE, xconst_nvc_sel = TRUE, nvc_num=5,
         method = "reml", penalty = "bic", maxiter = 30,
         covmodel="exp",enum = 200, bsize = 4000, cl=NULL )
```

Arguments

y	Vector of explained variables (N x 1)
x	Matrix of explanatory variables with spatially varying coefficients (SVC) (N x K)
xconst	Matrix of explanatory variables with constant coefficients (N x K_c). Default is NULL
coords	Matrix of spatial point coordinates (N x 2)
s_id	Optional. ID specifying groups modeling spatially dependent process (N x 1). If it is specified, group-level spatial process is estimated. It is useful for multilevel modeling (s_id is given by the group ID) and panel data modeling (s_id is given by individual location id). Default is NULL
x_nvc	If TRUE, SNVCs are assumed on x. Otherwise, SVCs are assumed. Default is FALSE
xconst_nvc	If TRUE, NVCs are assumed on xconst. Otherwise, constant coefficients are assumed. Default is FALSE
x_sel	If TRUE, type of coefficient (SVC or constant) on x is selected through a BIC (default) or AIC minimization. If FALSE, SVCs are assumed across x. Alternatively, x_sel can be given by column number(s) of x. For example, if x_sel = 2, the coefficient on the second explanatory variable in x is SVC and the other coefficients are constants. The Default is TRUE
x_nvc_sel	If TRUE, type of coefficient (NVC or constant) on x is selected through the BIC (default) or AIC minimization. If FALSE, NVCs are assumed across x. Alternatively, x_nvc_sel can be given by column number(s) of x. For example, if x_nvc_sel = 2, the coefficient on the second explanatory variable in x is NVC and the other coefficients are constants. The Default is TRUE
xconst_nvc_sel	If TRUE, type of coefficient (NVC or constant) on xconst is selected through the BIC (default) or AIC minimization. If FALSE, NVCs are assumed across xconst. Alternatively, xconst_nvc_sel can be given by column number(s) of

xconst. For example, if xconst_nvc_sel = 2, the coefficient on the second explanatory variable in xconst is NVC and the other coefficients are constants.The Default is TRUE

nvc_num
: Number of basis functions used to model NVC. An intercept and nvc_num natural spline basis functions are used to model each NVC. Default is 5

method
: Estimation method. Restricted maximum likelihood method ("reml") and maximum likelihood method ("ml") are available. Default is "reml"

penalty
: Penalty to select type of coefficients (SNVC, SVC, NVC, or constant) to stablize the estimates. The current options are "bic" for the Baysian information criterion-type penalty (N x log(K)) and "aic" for the Akaike information criterion (2K) (see Muller et al., 2013). Default is "bic"

maxiter
: Maximum number of iterations. Default is 30

covmodel
: Type of kernel to model spatial dependence. The currently available options are "exp" for the exponential kernel, "gau" for the Gaussian kernel, and "sph" for the spherical kernel

enum
: Number of Moran eigenvectors to be used for spatial process modeling (scalar). Default is 200

bsize
: Block/badge size. bsize x bsize elements are iteratively processed during the parallelized computation. Default is 4000

cl
: Number of cores used for the parallel computation. If cl = NULL, the number of available cores is detected. Default is NULL

Value

b_vc
: Matrix of estimated SNVC (= SVC + NVC) on x (N x K)

bse_vc
: Matrix of standard errors for the SNVCs on x (N x k)

z_vc
: Matrix of z-values for the SNVCs on x (N x K)

p_vc
: Matrix of p-values for the SNVCs on x (N x K)

B_vc_s
: List summarizing estimated SVCs (in SNVC) on x. The four elements are the SVCs (N x K), the standard errors (N x K), z-values (N x K), and p-values (N x K), respectively

B_vc_n
: List summarizing estimated NVCs (in SNVC) on x. The four elements are the NVCs (N x K), the standard errors (N x K), z-values (N x K), and p-values (N x K), respectively

c
: Matrix with columns for the estimated coefficients on xconst, their standard errors, z-values, and p-values (K_c x 4). Effective if xconst_nvc = FALSE

c_vc
: Matrix of estimated NVCs on xconst (N x K_c). Effective if xconst_nvc = TRUE

cse_vc
: Matrix of standard errors for the NVCs on xconst (N x k_c). Effective if xconst_nvc = TRUE

cz_vc
: Matrix of z-values for the NVCs on xconst (N x K_c). Effective if xconst_nvc = TRUE

cp_vc
: Matrix of p-values for the NVCs on xconst (N x K_c). Effective if xconst_nvc = TRUE

`s` List of variance parameters in the SNVC (SVC + NVC) on x. The first element is a 2 x K matrix summarizing variance parameters for SVC. The (1, k)-th element is the standard error of the k-th SVC, while the (2, k)-th element is the Moran's I value is scaled to take a value between 0 (no spatial dependence) and 1 (strongest spatial dependence). Based on Griffith (2003), the scaled Moran'I value is interpretable as follows: 0.25-0.50:weak; 0.50-0.70:moderate; 0.70-0.90:strong; 0.90-1.00:marked. The second element of s is the vector of standard errors of the NVCs

`s_c` Vector of standard errors of the NVCs on xconst

`vc` List indicating whether SVC/NVC are removed or not during the BIC/AIC minimization. 1 indicates not removed (replaced with constant) whreas 0 indicates removed

`e` Vector whose elements are residual standard error (resid_SE), adjusted conditional R2 (adjR2(cond)), restricted log-likelihood (rlogLik), Akaike information criterion (AIC), and Bayesian information criterion (BIC). When method = "ml", restricted log-likelihood (rlogLik) is replaced with log-likelihood (logLik)

`pred` Vector of predicted values (N x 1)

`resid` Vector of residuals (N x 1)

`other` List of other outputs, which are internally used

Author(s)

Daisuke Murakami

References

Muller, S., Scealy, J.L., and Welsh, A.H. (2013) Model selection in linear mixed models. Statistical Science, 28 (2), 136-167.

Murakami, D., Yoshida, T., Seya, H., Griffith, D.A., and Yamagata, Y. (2017) A Moran coefficient-based mixed effects approach to investigate spatially varying relationships. Spatial Statistics, 19, 68-89.

Murakami, D., and Griffith, D.A. (2019). Spatially varying coefficient modeling for large datasets: Eliminating N from spatial regressions. Spatial Statistics, 30, 39-64.

Murakami, D. and Griffith, D.A. (2019) A memory-free spatial additive mixed modeling for big spatial data. Japan Journal of Statistics and Data Science. DOI:10.1007/s42081-019-00063-x.

Murakami, D., and Griffith, D.A. (2020) Balancing spatial and non-spatial variations in varying coefficient modeling: a remedy for spurious correlation. ArXiv.

See Also

`resf_vc`

Examples

```
require(spdep)
data(boston)
```

```
y       <- boston.c[, "CMEDV"]
x       <- boston.c[,c("CRIM", "AGE")]
xconst  <- boston.c[,c("ZN","DIS","RAD","NOX",  "TAX","RM", "PTRATIO", "B")]
xgroup  <- boston.c[,"TOWN"]
coords  <- boston.c[,c("LON", "LAT")]

############## SVC modeling1 #################
######## (SVC on x; Constant coefficients on xconst)
#res     <- besf_vc(y=y,x=x,xconst=xconst,coords=coords, x_sel = FALSE )
#res
#plot_s(res,0) # Spatially varying intercept
#plot_s(res,1) # 1st SVC
#plot_s(res,2) # 2nd SVC

############## SVC modeling2 #################
######## (SVC or constant coefficients on x; Constant coefficients on xconst)
#res2   <- besf_vc(y=y,x=x,xconst=xconst,coords=coords )

############## SVC modeling3 #################
######## - Group-level SVC or constant coefficients on x
######## - Constant coefficients on xconst
#res3   <- besf_vc(y=y,x=x,xconst=xconst,coords=coords, s_id=xgroup)

############## SNVC modeling1 #################
######## - SNVC, SVC, NVC, or constant coefficients on x
######## - Constant coefficients on xconst

#res4   <- besf_vc(y=y,x=x,xconst=xconst,coords=coords, x_nvc =TRUE)

############## SNVC modeling2 #################
######## - SNVC, SVC, NVC, or constant coefficients on x
######## - NVC or Constant coefficients on xconst

#res5   <- besf_vc(y=y,x=x,xconst=xconst,coords=coords, x_nvc =TRUE, xconst_nvc=TRUE)
#plot_s(res5,0)            # Spatially varying intercept
#plot_s(res5,1)            # 1st SNVC (SVC + NVC)
#plot_s(res5,1,btype="svc")# SVC in the 1st SNVC
#plot_n(res5,1,xtype="x")  # NVC in the 1st NVC on x
#plot_n(res5,6,xtype="xconst")# NVC in the 6t NVC on xcnost
```

`coef_marginal` *Marginal effects evaluation*

Description

This function evaluates the marginal effects from x (dy/dx) based on the estimation result of `resf`. This funtion is for non-Gaussian models transforming y using `nongauss_y`.

Usage

```
coef_marginal( mod )
```

Arguments

mod	Output from resf

Value

b	Marginal effects from x (dy/dx)

See Also

resf

---

coef_marginal_vc — *Marginal effects evaluation from models with varying coefficients*

Description

This function evaluates the marginal effects from x (dy/dx) based on the estimation result of resf_vc. This funtion is for non-Gaussian models transforming y using nongauss_y.

Usage

```
coef_marginal_vc( mod )
```

Arguments

mod	Output from resf_vc

Value

b_vc	Matrix of the marginal effects of x (dy/dx) (N x K)
B_vc_n	Matrix of the sub-marginal effects of x explained by the spatially varying coefficients (N x K)
B_vc_s	Matrix of the sub-marginal effects explained by the non-spatially varying coefficients (N x K)
c	Matrix of the marginal effects of xconst (N x K_const)
other	List of other outputs, which are internally used

See Also

resf_vc

esf *Spatial regression with eigenvector spatial filtering*

Description

This function estimates the linear eigenvector spatial filtering (ESF) model. The eigenvectors are selected by a forward stepwise method.

Usage

```
esf( y, x = NULL, vif = NULL, meig, fn = "r2" )
```

Arguments

y	Vector of explained variables (N x 1)
x	Matrix of explanatory variables (N x K). Default is NULL
vif	Maximum acceptable value of the variance inflation factor (VIF) (scalar). For example, if vif = 10, eigenvectors are selected so that the maximum VIF value among explanatory variables and eigenvectors is equal to or less than 10. Default is NULL
meig	Moran eigenvectors and eigenvalues. Output from meigen or meigen_f
fn	Objective function for the stepwise eigenvector selection. The adjusted R2 ("r2"), AIC ("aic"), or BIC ("bic") are available. Alternatively, all the eigenvectors in meig are use if fn = "all". This is acceptable for large samples (see Murakami and Griffith, 2019). Default is "r2"

Value

b	Matrix with columns for the estimated coefficients on x, their standard errors, t-values, and p-values (K x 4)
s	Vector of statistics for the estimated spatial component (2 x 1). The first element is the standard error and the second element is the Moran's I value of the estimated spatially dependent component. The Moran's I value is scaled to take a value between 0 (no spatial dependence) and 1 (the maximum possible spatial dependence). Based on Griffith (2003), the scaled Moran'I value is interpretable as follows: 0.25-0.50:weak; 0.50-0.70:moderate; 0.70-0.90:strong; 0.90-1.00:marked
r	Matrix with columns for the estimated coefficients on Moran's eigenvectors, their standard errors, t-values, and p-values (L x 4)
vif	Vector of variance inflation factors of the explanatory variables (N x 1)
e	Vector whose elements are residual standard error (resid_SE), adjusted R2 (adjR2), log-likelihood (logLik), AIC, and BIC
sf	Vector of estimated spatial dependent component ($E\gamma$) (N x 1)
pred	Vector of predicted values (N x 1)
resid	Vector of residuals (N x 1)
other	List of other outputs, which are internally used

Author(s)

Daisuke Murakami

References

Griffith, D. A. (2003). Spatial autocorrelation and spatial filtering: gaining understanding through theory and scientific visualization. Springer Science & Business Media.

Tiefelsdorf, M., and Griffith, D. A. (2007). Semiparametric filtering of spatial autocorrelation: the eigenvector approach. Environment and Planning A, 39 (5), 1193-1221.

Murakami, D. and Griffith, D.A. (2019) Eigenvector spatial filtering for large data sets: fixed and random effects approaches. Geographical Analysis, 51 (1), 23-49.

See Also

resf

Examples

```
require(spdep)
data(boston)
y <- boston.c[, "CMEDV" ]
x <- boston.c[,c("CRIM","ZN","INDUS", "CHAS", "NOX","RM", "AGE")]
coords  <- boston.c[,c("LON", "LAT")]

#########Distance-based ESF
meig  <- meigen(coords=coords)
esfD <- esf(y=y,x=x,meig=meig, vif=5)
esfD

#########Fast approximation
meig_f<- meigen_f(coords=coords)
esfD <- esf(y=y,x=x,meig=meig_f, vif=10, fn="all")
esfD

############################Not run
#########Topoligy-based ESF (it is commonly used in regional science)
#
#cknn <- knearneigh(coordinates(coords), k=4) #4-nearest neighbors
#cmat <- nb2mat(knn2nb(cknn), style="B")
#meig <- meigen(cmat=cmat, threshold=0.25)
#esfT <- esf(y=y,x=x,meig=meig)
#esfT
```

---

lsem *Low rank spatial error model (LSEM) estimation*

Description

This function estimates the low rank spatial error model.

Usage

```
lsem( y, x, weig, method = "reml" )
```

Arguments

y	Vector of explained variables (N x 1)
x	Matrix of explanatory variables (N x K)
weig	eigenvectors and eigenvalues of a spatial weight matrix. Output from weigen
method	Estimation method. Restricted maximum likelihood method ("reml") and maximum likelihood method ("ml") are available. Default is "reml"

Value

b	Matrix with columns for the estimated coefficients on x, their standard errors, t-values, and p-values (K x 4)
s	Vector of estimated variance parameters (2 x 1). The first and the second elements denote the estimated rho parameter (sp_lambda) quantfying the scale of spatial dependent process, and the standard error of the process (sp_SE), respectively.
e	Vector whose elements are residual standard error (resid_SE), adjusted conditional R2 (adjR2(cond)), restricted log-likelihood (rlogLik), Akaike information criterion (AIC), and Bayesian information criterion (BIC). When method = "ml", restricted log-likelihood (rlogLik) is replaced with log-likelihood (logLik)
r	Vector of estimated random coefficients on the spatial eigenvectors (L x 1)
pred	Vector of predicted values (N x 1)
resid	Vector of residuals (N x 1)
other	List of other outputs, which are internally used

Author(s)

Daisuke Murakami

References

Murakami, D., Seya, H. and Griffith, D.A. (2018) Low rank spatial econometric models. Arxiv.

See Also

meigen, meigen_f

Examples

```
require(spdep)
data(boston)
y <- boston.c[, "CMEDV" ]
x <- boston.c[,c("CRIM","ZN","INDUS", "CHAS", "NOX","RM", "AGE",
                       "DIS" ,"RAD", "TAX", "PTRATIO", "B", "LSTAT")]
```

```
coords<- boston.c[,c("LON", "LAT")]
weig  <- weigen( coords )
res   <- lsem(y=y,x=x,weig=weig)
res
```

`lslm` *Low rank spatial lag model (LSLM) estimation*

Description

This function estimates the low rank spatial lag model.

Usage

```
lslm( y, x, weig, method = "reml", boot = FALSE, iter = 200 )
```

Arguments

`y`	Vector of explained variables (N x 1)
`x`	Matrix of explanatory variables (N x K)
`weig`	eigenvectors and eigenvalues of a spatial weight matrix. Output from `weigen`
`method`	Estimation method. Restricted maximum likelihood method ("reml") and maximum likelihood method ("ml") are available. Default is "reml"
`boot`	If it is TRUE, confidence intervals for the spatial dependence parameters (s), the mean direct effects (de), and the mean indirect effects (ie), are estimated through a parametric bootstrapping. Default is FALSE
`iter`	The number of bootstrap replicates. Default is 200

Value

`b`	Matrix with columns for the estimated coefficients on x, their standard errors, t-values, and p-values (K x 4)
`s`	Vector of estimated shrinkage parameters (2 x 1). The first and the second elements denote the estimated rho parameter (sp_rho) quantfying the scale of spatial dependence, and the standard error of the spatial dependent component (sp_SE), respectively. If boot = TRUE, their 95 percent confidence intervals and the resulting p-values are also provided
`e`	Vector whose elements are residual standard error (resid_SE), adjusted conditional R2 (adjR2(cond)), restricted log-likelihood (rlogLik), Akaike information criterion (AIC), and Bayesian information criterion (BIC). When method = "ml", restricted log-likelihood (rlogLik) is replaced with log-likelihood (logLik)
`de`	Matrix with columns for the estimated mean direct effects on x. If boot = TRUE, their 95 percent confidence intervals and the resulting p-values are also provided
`ie`	Matrix with columns for the estimated mean indirect effects on x. If boot = TRUE, their 95 percent confidence intervals and the resulting p-values are also provided

`r` Vector of estimated random coefficients on the spatial eigenvectors (L x 1)

`pred` Vector of predicted values (N x 1)

`resid` Vector of residuals (N x 1)

`other` List of other outputs, which are internally used

Author(s)

Daisuke Murakami

References

Murakami, D., Seya, H. and Griffith, D.A. (2018) Low rank spatial econometric models. Arxiv.

See Also

weigen, lsem

Examples

```
require(spdep)
data(boston)
y <- boston.c[, "CMEDV" ]
x <- boston.c[,c("CRIM","ZN","INDUS", "CHAS", "NOX","RM", "AGE",
                    "DIS" ,"RAD", "TAX", "PTRATIO", "B", "LSTAT")]
coords  <- boston.c[,c("LON", "LAT")]
weig    <- weigen(coords)
res     <- lslm(y=y,x=x,weig=weig)
## res  <- lslm(y=y,x=x,weig=weig, boot=TRUE)
res
```

---

meigen *Extraction of Moran's eigenvectors*

Description

This function calculates Moran eigenvectors and eigenvalues.

Usage

```
meigen( coords = NULL, model = "exp", threshold = 0,
        enum = NULL, cmat = NULL, s_id = NULL )
```

Arguments

`coords`	Matrix of spatial point coordinates (N x 2). If cmat is specified, it is ignored
`model`	Type of kernel to model spatial dependence. The currently available options are "exp" for the exponential kernel, "gau" for the Gaussian kernel, and "sph" for the spherical kernel. Default is "exp"
`threshold`	Threshold for the eigenvalues (scalar). Suppose that lambda_1 is the maximum eigenvalue, this function extracts eigenvectors whose corresponding eigenvalue is equal or greater than (threshold x lambda_1). threshold must be a value between 0 and 1. Default is zero (see Details)
`enum`	Optional. The muxmum acceptable mumber of eigenvectors to be extracted (scalar)
`cmat`	Optional. A user-specified spatial connectivity matrix (N x N). It must be provided when the user wants to use a spatial connectivity matrix other than the default matrices
`s_id`	Optional. Location/zone ID for modeling spatial effects across groups. If specified, Moran eigenvectors are extracted by groups. It is useful e.g. for multilevel modeling (s_id is the groups) and panel data modeling (s_id is given by individual location id). Default is NULL

Details

If cmat is not provided and model = "exp" (default), this function extracts Moran eigenvectors from MCM, where M = I - 11'/N is a centering operator. C is a N x N connectivity matrix whose (i, j)-th element equals exp(-d(i,j)/h), where d(i,j) is the Euclidean distance between the sample sites i and j, and h is given by the maximum length of the minimum spanning tree connecting sample sites (see Dray et al., 2006). If cmat is provided, this function performs the same calculation after C is replaced with cmat.

If threshold is not provided (default), all the eigenvectors corresponding to positive eigenvalue, explaining positive spatial dependence, are extracted to model positive spatial dependence. threshold = 0.00 or 0.25 are standard assumptions (see Griffith, 2003; Murakami and Griffith, 2015).

Value

`sf`	Matrix of the first L eigenvectors (N x L)
`ev`	Vector of the first L eigenvalues (L x 1)
`ev_full`	Vector of all eigenvalues (N x 1)
`other`	List of other outcomes, which are internally used

Author(s)

Daisuke Murakami

References

Dray, S., Legendre, P., and Peres-Neto, P.R. (2006) Spatial modelling: a comprehensive framework for principal coordinate analysis of neighbour matrices (PCNM). Ecological Modelling, 196 (3), 483-493.

Griffith, D.A. (2003) Spatial autocorrelation and spatial filtering: gaining understanding through theory and scientific visualization. Springer Science & Business Media.

Murakami, D. and Griffith, D.A. (2015) Random effects specifications in eigenvector spatial filtering: a simulation study. Journal of Geographical Systems, 17 (4), 311-331.

See Also

`meigen_f` for fast eigen-decomposition

`meigen0` *Nystrom extension of Moran eigenvectors*

Description

This function estimates Moran eigenvectors at unobserved sites using the Nystrom extension.

Usage

```
meigen0( meig, coords0, s_id0 = NULL )
```

Arguments

`coords0`	Matrix of spatial point coordinates of unobserved sites (N_0 x 2)
`meig`	Moran eigenvectors and eigenvalues. Output from `meigen` or `meigen_f`
`s_id0`	Optional. ID specifying groups modeling spatial effects (N_0 x 1). If specified, Moran eigenvectors are extracted by groups. It is useful e.g. for multilevel modeling (s_id is the groups) and panel data modeling (s_id is given by individual location id). Default is NULL

Value

`sf`	Matrix of the first L eigenvectors at unobserved sites (N_0 x L)
`ev`	Vector of the first L eigenvalues (L x 1)
`ev_full`	Vector of all eigenvalues (N x 1)

Author(s)

Daisuke Murakami

References

Drineas, P. and Mahoney, M.W. (2005) On the Nystrom method for approximating a gram matrix for improved kernel-based learning. Journal of Machine Learning Research, 6 (2005), 2153-2175.

See Also

meigen, meigen_f

---

meigen_f — *Fast approximation of Moran eigenvectors*

Description

This function performs a fast approximation of Moran eigenvectors and eigenvalues.

Usage

```
meigen_f( coords, model = "exp", enum = 200, s_id = NULL )
```

Arguments

coords	Matrix of spatial point coordinates (N x 2)
model	Type of kernel to model spatial dependence. The currently available options are "exp" for the exponential kernel, "gau" for the Gaussian kernel, and "sph" for the spherical kernel. Default is "exp"
enum	Number of eigenvectors and eigenvalues to be extracted (scalar). Default is 200
s_id	Optional. Location/zone ID for modeling spatial effects across groups. If specified, Moran eigenvectors are extracted by groups. It is useful e.g. for multilevel modeling (s_id is the groups) and panel data modeling (s_id is given by individual location id). Default is NULL

Details

This function extracts approximated Moran eigenvectors from MCM. M = I - 11'/N is a centering operator, and C is a spatial connectivity matrix whose (i, j)-th element is given by exp(-d(i,j)/h), where d(i,j) is the Euclidean distance between the sample sites i and j, and h is a range parameter given by the maximum length of the minimum spanning tree connecting sample sites (see Dray et al., 2006).

Following a simulation result that 200 eigenvectors are sufficient for accurate approximation of ESF models (Murakami and Griffith, 2019), this function approximates the 200 eigenvectors corresponding to the 200 largest eigenvalues by default (i.e., enum = 200). If enum is given by a smaller value like 100, the computation time will be shorter, but with greater approximation error. Eigenvectors corresponding to negative eigenvalues are omitted from the enum eigenvectors.

Value

sf	Matrix of the first L approximated eigenvectors (N x L)
ev	Vector of the first L approximated eigenvalues (L x 1)
ev_full	Vector of all approximated eigenvalues (enum x 1)
other	List of other outcomes, which are internally used

Author(s)

Daisuke Murakami

References

Dray, S., Legendre, P., and Peres-Neto, P.R. (2006) Spatial modelling: a comprehensive framework for principal coordinate analysis of neighbour matrices (PCNM). Ecological Modelling, 196 (3), 483-493.

Murakami, D. and Griffith, D.A. (2019) Eigenvector spatial filtering for large data sets: fixed and random effects approaches. Geographical Analysis, 51 (1), 23-49.

See Also

meigen

`nongauss_y` *Parameter setup for modeling non-Gaussian continuous data and count data*

Description

Parameter setup for modeling non-Gaussian continuous data and count data. The SAL transformation (see details) is used to model a wide variety of non-Gaussian data without explicitly assuming data distribution (see Murakami et al., 2021 for further detail). In addition, Box-Cox transformation is used for non-negative continuous variables while another transformation approximating overdispersed Poisson distribution is used for count variables. The output from this function is used as an input of the resf and resf_vc functions. For further details about its implementation and case study examples, see Murakami (2021).

Usage

```
nongauss_y( y_type = "continuous", y_nonneg = FALSE, tr_num = 0 )
```

Arguments

y_type	Type of explained variables y. "continuous" for continuous variables and "count" for count variables
y_nonneg	Effective if y_type = "continuous". TRUE if y cannot take negative value. If y_nonneg = TRUE and tr_num = 0, the Box-Cox transformation is applied to y. If y_nonneg = TRUE and tr_num > 0, the Box-Cox transformation is applied first to roughly Gaussianize y. Then, the SAL transformation is iterated tr_num times to improve the modeling accuracy. Default is FALSE
tr_num	Number of the SAL transformations (SinhArcsinh and Affine, where the use of "L" stems from the "Linear") applied to Gaussianize y. Default is 0

Details

If tr_num >0, the SAL transformation is iterated tr_num times to Gaussianize y. The SAL transformation is defined as SAL(y)=a+b*sinh(c*arcsinh(y)-d) where a,b,c,d are parameters. Based on Rios and Tobar (2019), the iteration of the SAL transformation approximates a wide variety of non-Gaussian distributions without explicitly assuming data distribution. The resf and resf_vc functions return tr_par, which is a list whose k-th element includes the a,b,c,d parameters used for the k-th SAL transformation.

In addition, for non-negative y (y_nonneg = TRUE), the Box-Cox transformation is applied prior to the iterative SAL transformation. tr_num and y_nonneg can be selected by comparing the BIC (or AIC) values across models. This compositionally-warped spatial regression approach is detailed in Murakami et al. (2021).

For count data (y_type = "count"), an overdispersed Poisson distribution (Gaussian approximation) is assumed. If tr_num > 0, the distribution is adjusted to fit the data (y) through the iterative SAL transformations. y_nonneg is ignored if y_type = "count".

Value

`nongauss`	List of parameters for modeling non-Gaussian data

References

Rios, G. and Tobar, F. (2019) Compositionally-warped Gaussian processes. Neural Networks, 118, 235-246.

Murakami, D. (2021) Transformation-based generalized spatial regression using the spmoran package: Case study examples, ArXiv.

Murakami, D., Kajita, M., Kajita, S. and Matsui, T. (2021) Compositionally-warped additive mixed modeling for a wide variety of non-Gaussian data. Spatial Statistics, 43, 100520.

Murakami, D., & Matsui, T. (2021). Improved log-Gaussian approximation for over-dispersed Poisson regression: application to spatial analysis of COVID-19. ArXiv, 2104.13588.

See Also

`resf`, `resf_vc`

Examples

```
###### Regression for non-negative data (BC trans.)
ng1  <-nongauss_y( y_nonneg = TRUE )
ng1

###### General non-Gaussian regression for continuous data (two SAL trans.)
ng2  <-nongauss_y( tr_num = 2 )
ng2

###### General non-Gaussian regression for non-negative continuous data
ng3  <-nongauss_y( y_nonneg = TRUE, tr_num = 5 )
ng3
```

```
###### Over-dispersed Poisson regression for count data
ng4  <-nongauss_y( y_type = "count" )
ng4

###### A general non-Gaussian regression for count data
ng5  <-nongauss_y( y_type = "count", tr_num = 5 )
ng5

############################## Fitting example
require(spdep);require(Matrix)
data(boston)
y     <- boston.c[, "CMEDV" ]
x     <- boston.c[,c("CRIM","ZN","INDUS", "CHAS", "NOX","RM", "AGE",
                     "DIS" ,"RAD", "TAX", "PTRATIO", "B", "LSTAT")]
xgroup<- boston.c[,"TOWN"]
coords<- boston.c[,c("LON","LAT")]
meig  <- meigen(coords=coords)
res   <- resf(y = y, x = x, meig = meig,nongauss=ng2)
res                   # Estimation results

plot(res$pdf,type="l") # Estimated probability density function
res$skew_kurt          # Skew and kurtosis of the estimated PDF
res$pred_quantile[1:2,]# predicted value by quantile
coef_marginal(res)     # Estimated marginal effects (dy/dx)
```

---

plot_n *Plot non-spatially varying coefficients (NVCs)*

Description

This function plots non-spatially varying coefficients (NVCs; coefficients varying with respect to explanatory variable value) and their 95 percent confidence intervals

Usage

```
plot_n( mod, xnum = 1, xtype = "x", cex.lab = 20,
        cex.axis = 15, lwd = 1.5, ylim = NULL, nmax = 20000 )
```

Arguments

mod	Outpot from resf, besf, resf_vc, or besf_vc function
xnum	The NVC on the xnum-th explanatory variable is plotted. Default is 1
xtype	Effective for resf_vc and besf_vc. If "x", the num-th NVC in the spatially and non-spatially varying coefficients on x is plotted. If "xconst", the num-th NVC on xconst is plotted. Default is "x"
cex.lab	The size of the x and y axis labels
cex.axis	The size of the tick label numbers

lwd The width of the line drawing the coefficient estimates

ylim The limints of the y-axis

nmax If sample size exceeds nmax, nmax samples are randomly selected and plotted. Default is 20,000

See Also

resf, besf, resf_vc, besf_vc

---

plot_qr *Plot quantile regression coefficients estimated from SF-UQR*

Description

This function plots regression coefficients estimated from the spatial filter unconditional quantile regression (SF-UQR) model.

Usage

```
plot_qr( mod, pnum = 1, par = "b", cex.main = 20, cex.lab = 18, cex.axis = 15, lwd = 1.5 )
```

Arguments

mod Outpot from the resf_qr function

pnum A number specifying the parameter being plotted. If par = "b", the coefficients on the pnum-th explanatory variable are plotted (intercepts are plotted if pnum = 1). If par = "s" and pnum = 1, the estimated standard errors for the reidual spatial process are plotted. If par = "s" and pnum = 2, the Moran's I values of the residual spatial process are plotted. The Moran's I value is scaled to take a value between 0 (no spatial dependence) and 1 (the maximum possible spatial dependence). Based on Griffith (2003), the scaled Moran'I value is interpretable as follows: 0.25-0.50:weak; 0.50-0.70:moderate; 0.70-0.90:strong; 0.90-1.00:marked

par If it is "b", regression coefficeints are plotted. If it is "s", shrinkage (variance) parameters for the residual spatial process are plotted. Default is "b"

cex.main Graphical parameter specifying the size of the main title

cex.lab Graphical parameter specifying the size of the x and y axis labels

cex.axis Graphical parameter specifying the size of the tick label numbers

lwd Graphical parameters specifying the width of the line drawing the coefficient estimates

Note

See par for the graphical parameters

See Also

resf_qr

---

plot_s *Mapping spatially (and non-spatially) varying coefficients (SVCs or SNVC)*

Description

This function plots spatially and non-spatially varying coefficients (SNVC) or spatially varying coefficients (SVC). Note that SNVC = SVC + NVC (NVC is a coefficient varying with respect to explanatory variable value)

Usage

```
plot_s( mod, xnum = 0, btype = "snvc", xtype = "x", pmax = NULL, ncol = 8,
        col = NULL, inv =FALSE, brks = "regular", cex = 1, nmax = 20000)
```

Arguments

mod	Outpot from resf, besf, resf_vc, or besf_vc function
xnum	For resf_vc and besf_vc, xnum-th S(N)VC on x is plotted. If num = 0, spatially varying intercept is plotted. For resf and besf, estimated spatially dependent component in the residuals is plotted irrespective of the xnum value. Default is 0
btype	Effective for resf_vc and besf_vc. If "snvc" (default), SNVC (= SVC + NVC) is plotted. If "svc" , SVC is plotted. If "nvc", NVC is plotted
xtype	If "x" (default), coefficients on x is plotted. If "xconst", those on xconst is plotted
pmax	The maximum p-value for the S(N)VC to be displayed. For example, if pmax = 0.05, only coefficients that are statistically significant at the 5 percent level are plotted. If NULL, all the coefficients are plotted. Default is NULL
ncol	Number of colors in the color palette. Default is 8
col	Color palette used for the mapping. If NULL, the blue-pink-yellow color scheme is used. Palettes in the RColorBrewer package are available. Default is NULL
inv	If TRUE, the color palett is inverted. Default is FALSE
brks	If "regular", color is changed at regular intervals. If "quantile", color is changed for each quantile
cex	Size of the dots representing sample sites
nmax	If sample size exceeds nmax, nmax samples are randomly selected and plotted. Default is 20,000

See Also

resf, besf, resf_vc, besf_vc

predict0 *Spatial predictions*

Description

This function predicts explained variables using eigenvector spatial filtering (ESF) or random effects ESF. The Nystrom extension is used to perform a prediction minimizing the expected prediction error

Usage

```
predict0( mod, meig0, x0 = NULL, xgroup0 = NULL, offset0 = NULL,
weight0 = NULL, compute_se=FALSE, compute_quantile = FALSE )
```

Arguments

mod	Output from esf or resf
meig0	Moran eigenvectors at predicted sites. Output from meigen0
x0	Matrix of explanatory variables at predicted sites (N_0 x K). Default is NULL
xgroup0	Matrix of group IDs that may be group IDs (integers) or group names (N_0 x K_group). Default is NULL
offset0	Vector of offset variables at predicted sites (N_0 x 1). Effective if y is count (see nongauss_y). Default is NULL
weight0	Vector of weights for predicted sites (N_0 x 1). Required if compute_se = TRUE or compute_quantile = TRUE
compute_se	If TRUE, predictive standard error is evaulated. It is currently supported only for continuous variables. If nongauss is specified in mod, standard error for the transformed y is evaluated. Default is FALSE
compute_quantile	If TRUE, Matrix of the quantiles for the predicted values (N x 15) is evaulated. It is currently supported only for continuous variables. Default is FALSE

Value

pred	Matrix with the first column for the predicted values (pred). The second and the third columns are the predicted trend component (xb) and the residual spatial process (sf_residual). If xgroup0 is specified, the fourth column is the predicted group effects (group). If tr_num > 0 or tr_nonneg ==TRUE (i.e., y is transformed) in resf, another column including the predicted values in the transformed/normalized scale (pred_trans) is inserted as the second column. In addition, if compute_quantile =TRUE, predictive standard errors (pred_se) is evaluated and inserted as another column
pred_quantile	Effective if compute_quantile = TRUE. Matrix of the quantiles for the predicted values (N x 15). It is useful to evaluate uncertainty in the predictive value

c_vc — Matrix of estimated non-spatially varying coefficients (NVCs) on x0 (N x K). Effective if nvc =TRUE in resf

cse_vc — Matrix of standard errors for the NVCs on x0 (N x K).Effective if nvc =TRUE in resf

ct_vc — Matrix of t-values for the NVCs on x0 (N x K). Effective if nvc =TRUE in resf

cp_vc — Matrix of p-values for the NVCs on x0 (N x K). Effective if nvc =TRUE in resf

References

Drineas, P. and Mahoney, M.W. (2005) On the Nystrom method for approximating a gram matrix for improved kernel-based learning. Journal of Machine Learning Research, 6 (2005), 2153-2175.

See Also

meigen0, predict0_vc

Examples

```
require(spdep)
data(boston)
samp    <- sample( dim( boston.c )[ 1 ], 400)

d       <- boston.c[ samp, ]  ## Data at observed sites
y       <- d[, "CMEDV"]
x       <- d[,c("ZN","INDUS", "NOX","RM", "AGE", "DIS")]
coords  <- d[,c("LON", "LAT")]

d0      <- boston.c[-samp, ]  ## Data at unobserved sites
y0     <- d0[, "CMEDV"]
x0      <- d0[,c("ZN","INDUS", "NOX","RM", "AGE", "DIS")]
coords0 <- d0[,c("LON", "LAT")]

############ Model estimation
meig    <- meigen( coords = coords )
mod     <- resf(y=y, x=x, meig=meig)
## or
# mod   <- esf(y=y,x=x,meig=meig)

############ Spatial prediction
meig0  <- meigen0( meig = meig, coords0 = coords0 )
pred0   <- predict0( mod = mod, x0 = x0, meig0 = meig0 )
pred0$pred[1:10,]

######################## If NVCs are assumed
#mod2   <- resf(y=y, x=x, meig=meig, nvc=TRUE)
#pred02  <- predict0( mod = mod2, x0 = x0, meig0 = meig0 )
#pred02$pred[1:10,]  # Predicted explained variables
#pred02$c_vc[1:10,]  # Predicted NVCs
```

predict0_vc *Spatial predictions for explained variables and spatially varying coefficients*

Description

This function predicts explained variables and spatially and non-spatially varying coefficients. The Nystrom extension is used to perform a prediction minimizing the expected prediction error

Usage

```
predict0_vc( mod, meig0, x0 = NULL, xgroup0 = NULL, xconst0 = NULL,
        offset0 = NULL, weight0 = NULL, compute_se=FALSE, compute_quantile = FALSE )
```

Arguments

mod	Output from resf_vc or besf_vc
meig0	Moran eigenvectors at predicted sites. Output from meigen0
x0	Matrix of explanatory variables at predicted sites whose coefficients are allowed to vary across geographical space (N_0 x K). Default is NULL
xgroup0	Matrix of group indeces that may be group IDs (integers) or group names (N_0 x K_group). Default is NULL
xconst0	Matrix of explanatory variables at predicted sites whose coefficients are assumed constant (or NVC) across space (N_0 x K_const). Default is NULL
offset0	Vector of offset variables at predicted sites (N x 1). Available if y is count (see nongauss_y). Default is NULL
weight0	Vector of weights for predicted sites (N_0 x 1). Required if compute_se = TRUE or compute_quantile = TRUE
compute_se	If TRUE, predictive standard error is evaulated. It is currently supported only for continuous variables. If nongauss is specified in mod, standard error for the transformed y is evaluated. Default is FALSE
compute_quantile	If TRUE, Matrix of the quantiles for the predicted values (N x 15) is evaulated. Default is FALSE

Value

pred	Matrix with the first column for the predicted values (pred). The second and the third columns are the predicted trend component (i.e., component explained by x0 and xconst0) (xb) and the residual spatial process (sf_residual). If xgroup0 is specified, the fourth column is the predicted group effects (group) If tr_num > 0 or tr_nonneg ==TRUE (i.e., y is transformed) in resf_vc, another column including the predicted values in the transformed/normalized scale (pred_trans) is inserted into the second column

b_vc	Matrix of estimated spatially (and non-spatially) varying coefficients (S(N)VCs) on x0 (N_0 x K)
bse_vc	Matrix of estimated standard errors for the S(N)VCs (N_0 x K)
t_vc	Matrix of estimated t-values for the S(N)VCs (N_0 x K)
p_vc	Matrix of estimated p-values for the S(N)VCs (N_0 x K)
c_vc	Matrix of estimated non-spatially varying coefficients (NVCs) on xconst0 (N_0 x K)
cse_vc	Matrix of estimated standard errors for the NVCs (N_0 x K)
ct_vc	Matrix of estimated t-values for the NVCs (N_0 x K)
cp_vc	Matrix of estimated p-values for the NVCs (N_0 x K)

References

Drineas, P. and Mahoney, M.W. (2005) On the Nystrom method for approximating a gram matrix for improved kernel-based learning. Journal of Machine Learning Research, 6 (2005), 2153-2175.

Murakami, D., Yoshida, T., Seya, H., Griffith, D.A., and Yamagata, Y. (2017) A Moran coefficient-based mixed effects approach to investigate spatially varying relationships. Spatial Statistics, 19, 68-89.

See Also

meigen0, predict0

Examples

```
require(spdep)
data(boston)
samp    <- sample( dim( boston.c )[ 1 ], 300)

d       <- boston.c[ samp, ]    ## Data at observed sites
y       <- d[, "CMEDV"]
x       <- d[,c("ZN", "LSTAT")]
xconst  <- d[,c("CRIM", "NOX", "AGE", "DIS", "RAD", "TAX", "PTRATIO", "B", "RM")]
coords  <- d[,c("LON", "LAT")]

d0      <- boston.c[-samp, ]    ## Data at unobserved sites
y0      <- d0[, "CMEDV"]
x0      <- d0[,c("ZN", "LSTAT")]
xconst0 <- d0[,c("CRIM", "NOX", "AGE", "DIS", "RAD", "TAX", "PTRATIO", "B", "RM")]
coords0 <- d0[,c("LON", "LAT")]

############ Model estimation
meig    <- meigen( coords = coords )
mod     <- resf_vc(y=y, x=x, xconst=xconst, meig=meig )

############ Spatial prediction of y and spatially varying coefficients
meig0  <- meigen0( meig = meig, coords0 = coords0 )
pred0   <- predict0_vc( mod = mod, x0 = x0, xconst0=xconst0, meig0 = meig0 )
```

```
pred0$pred[1:10,]  # Predicted explained variables
pred0$b_vc[1:10,]  # Predicted SVCs
pred0$bse_vc[1:10,]# Predicted standard errors of the SVCs
pred0$t_vc[1:10,]  # Predicted t-values of the SNVCs
pred0$p_vc[1:10,]  # Predicted p-values of the SNVCs

plot(y0,pred0$pred[,1]);abline(0,1)

############ or spatial prediction of spatially varying coefficients only
# pred00  <- predict0_vc( mod = mod, meig0 = meig0 )
# pred00$b_vc[1:10,]
# pred00$bse_vc[1:10,]
# pred00$t_vc[1:10,]
# pred00$p_vc[1:10,]

######################## If SNVCs are assumed on x
# mod2    <- resf_vc(y=y, x=x, xconst=xconst, meig=meig, x_nvc=TRUE,xconst_nvc=TRUE )
# pred02  <- predict0_vc( mod = mod2, x0 = x0, xconst0=xconst0 ,meig0 = meig0 )
# pred02$pred[1:10,]  # Predicted explained variables
# pred02$b_vc[1:10,]  # Predicted SNVCs
# pred02$bse_vc[1:10,]# Predicted standard errors of the SNVCs
# pred02$t_vc[1:10,]  # Predicted t-values of the SNVCs
# pred02$p_vc[1:10,]  # Predicted p-values of the SNVCs
# plot(y0,pred02$pred[,1]);abline(0,1)
```

---

resf *Gaussian and non-Gaussian spatial regression models*

Description

This model estimates regression coefficients, coefficients varying depending on x (non-spatially varying coefficients; NVC), group effects, and residual spatial dependence. The random-effects eigenvector spatial filtering, which is an approximate Gaussian process approach, is used for modeling the spatial dependence. The explained variables are transformed to fit the data distribution if nongauss is specified. Thus, this function is available for modeling Gaussian and non-Gaussian continuous data and count data (see nongauss_y).

Usage

```
resf( y, x = NULL, xgroup = NULL, weight = NULL, offset = NULL,
      nvc = FALSE, nvc_sel = TRUE, nvc_num = 5, meig,
      method = "reml", penalty = "bic", nongauss = NULL )
```

Arguments

y	Vector of explained variables (N x 1)
x	Matrix of explanatory variables (N x K). Default is NULL

xgroup	Matrix of group IDs. The IDs may be group numbers or group names (N x K_group). Default is NULL
weight	Vector of weights for samples (N x 1). If non-NULL, the adjusted R-squared value is evaluated for weighted explained variables. Default is NULL
offset	Vector of offset variables (N x 1). Available if y is count (y_type = "count" is specified in the nongauss_y function). Default is NULL
nvc	If TRUE, non-spatiallly varying coefficients (NVCs; coefficients varying with respect to explanatory variable value) are asumed. If FALSE, constant coefficients are assumed. Default is FALSE
nvc_sel	If TRUE, type of each coefficient (NVC or constant) is selected through a BIC (default) or AIC minimization. If FALSE, NVCs are assumed across x. Alternatively, nvc_sel can be given by column number(s) of x. For example, if nvc_sel = 2, the coefficient on the second explanatory variable is NVC and the other coefficients are constants. Default is TRUE
nvc_num	Number of basis functions used to model NVC. An intercept and nvc_num natural spline basis functions are used to model each NVC. Default is 5
meig	Moran eigenvectors and eigenvalues. Output from meigen or meigen_f
method	Estimation method. Restricted maximum likelihood method ("reml") and maximum likelihood method ("ml") are available. Default is "reml"
penalty	Penalty to select type of coefficients (NVC or constant) to stablize the estimates. The current options are "bic" for the Baysian information criterion-type penalty (N x log(K)) and "aic" for the Akaike information criterion (2K). Default is "bic"
nongauss	Parameter setup for modeling non-Gaussian continuous data or count data. Output from nongauss_y

Details

This function estimates Gaussian and non-Gaussian spatial model for continuous and count data. For non-Gaussian modeling, see nongauss_y.

Value

b	Matrix with columns for the estimated constant coefficients on x, their standard errors, t-values, and p-values (K x 4)
b_g	List of K_group matrices with columns for the estimated group effects, their standard errors, and t-values
c_vc	Matrix of estimated NVCs on x (N x K). Effective if nvc = TRUE
cse_vc	Matrix of standard errors for the NVCs on x (N x K). Effective if nvc = TRUE
ct_vc	Matrix of t-values for the NVCs on x (N x K). Effective if nvc = TRUE
cp_vc	Matrix of p-values for the NVCs on x (N x K). Effective if nvc = TRUE
s	Vector of estimated variance parameters (2 x 1). The first and the second elements are the standard error and the Moran's I value of the estimated spatially dependent process, respectively. The Moran's I value is scaled to take a

value between 0 (no spatial dependence) and 1 (the maximum possible spatial dependence). Based on Griffith (2003), the scaled Moran'I value is interpretable as follows: 0.25-0.50:weak; 0.50-0.70:moderate; 0.70-0.90:strong; 0.90-1.00:marked

s_c
: Vector of standard errors of the NVCs on xconst

s_g
: Vector of estimated standard errors of the group effects

e
: Error statistics. When y_type="continuous", it includes residual standard error (resid_SE), adjusted conditional R2 (adjR2(cond)), restricted log-likelihood (rlogLik), Akaike information criterion (AIC), and Bayesian information criterion (BIC). rlogLik is replaced with log-likelihood (logLik) if method = "ml". resid_SE is replaced with the residual standard error for the transformed y (resid_SE_trans) if nongauss is specified. When y_type="count", the error statistics includes root mean squared error (RMSE), Gaussian likelihood approximating the model, AIC and BIC based on the likelihood, and the proportion of the null deviance explained by the model (deviance explained (%)). deviance explained, which is also used in the mgcv package, corresponds to the adjusted R2 in case of the linear regression

vc
: List indicating whether NVC are removed or not during the BIC/AIC minimization. 1 indicates not removed whreas 0 indicates removed

r
: Vector of estimated random coefficients on Moran's eigenvectors (L x 1)

sf
: Vector of estimated spatial dependent component (N x 1)

pred
: Matrix of predicted values for y (pred) and their standard errors (pred_se) (N x 2). If y is transformed by specifying nongauss_y, the predicted values in the transformed/normalized scale are added as another column named pred_trans

pred_quantile
: Matrix of the quantiles for the predicted values (N x 15). It is useful to evaluate uncertainty in the predictive value

tr_par
: List of the parameter estimates for the tr_num SAL transformations. The k-th element of the list includes the four parameters for the k-th SAL transformation (see nongauss_y)

tr_bpar
: The estimated parameter in the Box-Cox transformation

tr_y
: Vector of the transformed explaied variables

resid
: Vector of residuals (N x 1)

pdf
: Matrix whose first column consists of evenly spaced values within the value range of y and the second column consists of the estimated value of the probability density function for y if y_type in nongauss_y is "continuous" and probability mass function (PMF) if y_type = "count". If offset is specified (and y_type = "count"), the PMF given median offset value is evaluated

skew_kurt
: Skewness and kurtosis of the estimated probability density/mass function of y

other
: List of other outputs, which are internally used

Author(s)

Daisuke Murakami

References

Murakami, D. and Griffith, D.A. (2015) Random effects specifications in eigenvector spatial filtering: a simulation study. Journal of Geographical Systems, 17 (4), 311-331.

Murakami, D., and Griffith, D.A. (2020) Balancing spatial and non-spatial variations in varying coefficient modeling: a remedy for spurious correlation. Geographical Analysis, DOI: 10.1111/gean.12310.

Murakami, D., Kajita, M., Kajita, S. and Matsui, T. (2021) Compositionally-warped additive mixed modeling for a wide variety of non-Gaussian data. Spatial Statistics, 43, 100520.

See Also

meigen, meigen_f, coef_marginal, besf

Examples

```
require(spdep);require(Matrix)
data(boston)
y     <- boston.c[, "CMEDV" ]
x     <- boston.c[,c("CRIM","ZN","INDUS", "CHAS", "NOX","RM", "AGE",
                     "DIS" ,"RAD", "TAX", "PTRATIO", "B", "LSTAT")]
xgroup<- boston.c[,"TOWN"]
coords<- boston.c[,c("LON","LAT")]
meig  <- meigen(coords=coords)
# meig<- meigen_f(coords=coords)  ## for large samples

#####################################################
######## Gaussian spatial regression models #########
#####################################################

res   <- resf(y = y, x = x, meig = meig)
res
plot_s(res)    ## spatially dependent component (intercept)

######## Group-wise random intercepts ###############
#res2 <- resf(y = y, x = x, meig = meig, xgroup = xgroup)

######## Group-wise random intercepts and ###########
######## Group-level spatial dependence   ###########

#meig_g<- meigen(coords=coords, s_id = xgroup)
#res3  <- resf(y = y, x = x, meig = meig_g, xgroup = xgroup)

######## Coefficients varying depending on x ########

#res4  <- resf(y = y, x = x, meig = meig, nvc = TRUE)
#res4

#plot_s(res4)   # spatially dependent component (intercept)
#plot_s(res4,5) # spatial plot of the 5-th NVC
#plot_s(res4,6) # spatial plot of the 6-th NVC
#plot_s(res4,13)# spatial plot of the 13-th NVC
```

```
#plot_n(res4,5) # 1D plot of the 5-th NVC
#plot_n(res4,6) # 1D plot of the 6-th NVC
#plot_n(res4,13)# 1D plot of the 13-th NVC

#####################################################
###### Non-Gaussian spatial regression models #######
#####################################################

#### Generalized model for continuous data ##############
# - Data distribution is estimated

#ng5    <- nongauss_y( tr_num = 2 )# 2 SAL transformations to Gaussianize y
#res5   <- resf(y = y, x = x, meig = meig, nongauss = ng5)
#res5              ## tr_num may be selected by comparing BIC (or AIC)

#plot(res5$pdf,type="l") # Estimated probability density function
#res5$skew_kurt          # Skew and kurtosis of the estimated PDF
#res5$pred_quantile[1:2,]# predicted value by quantile
#coef_marginal(res5)     # Estimated marginal effects (dy/dx)


#### Generalized model for non-negative continuous data #
# - Data distribution is estimated

#ng6    <- nongauss_y( tr_num = 2, y_nonneg = TRUE )
#res6   <- resf(y = y, x = x, meig = meig, nongauss = ng6 )
#coef_marginal(res6)

#### Overdispersed Poisson model for count data #####
# - y is assumed as a count data

#ng7    <- nongauss_y( y_type = "count" )
#res7   <- resf(y = y, x = x, meig = meig, nongauss = ng7 )


#### Generalized model for count data ###############
# - y is assumed as a count data
# - Data distribution is estimated

#ng8    <- nongauss_y( y_type = "count", tr_num = 2 )
#res8   <- resf(y = y, x = x, meig = meig, nongauss = ng8 )
```

`resf_qr` *Spatial filter unconditional quantile regression*

Description

This function estimates the spatial filter unconditional quantile regression (SF-UQR) model.

Usage

```
resf_qr( y, x = NULL, meig, tau = NULL, boot = TRUE, iter = 200, cl=NULL )
```

Arguments

y	Vector of explained variables (N x 1)
x	Matrix of explanatory variables (N x K). Default is NULL
meig	Moran eigenvectors and eigenvalues. Output from meigen or meigen_f
tau	The quantile(s) to be modeled. It must be a number (or a vector of numbers) strictly between 0 and 1. By default, tau = c(0.1, 0.2, ..., 0.9)
boot	If it is TRUE, confidence intervals of regression coefficients are estimated by a semiparametric bootstrapping. Default is TRUE
iter	The number of bootstrap replications. Default is 200
cl	Number of cores used for the parallel computation. If cl=NULL, which is the default, the number of available cores is detected and used

Value

b	Matrix of estimated regression coefficients (K x Q), where Q is the number of quantiles (i.e., the length of tau)
r	Matrix of estimated random coefficients on Moran eigenvectors (L x Q)
s	Vector of estimated variance parameters (2 x 1). The first and the second elements denote the standard error and the Moran's I value of the estimated spatially dependent component, respectively. The Moran's I value is scaled to take a value between 0 (no spatial dependence) and 1 (the maximum possible spatial dependence). Based on Griffith (2003), the scaled Moran'I value is interpretable as follows: 0.25-0.50:weak; 0.50-0.70:moderate; 0.70-0.90:strong; 0.90-1.00:marked
e	Vector whose elements are residual standard error (resid_SE) and adjusted quasi conditional R2 (quasi_adjR2(cond))
B	Q matrices (K x 4) summarizing bootstrapped estimates for the regression coefficients. Columns of these matrices consist of the estimated coefficients, the lower and upper bounds for the 95 percent confidencial intervals, and p-values. It is returned if boot = TRUE
S	Q matrices (2 x 3) summarizing bootstrapped estimates for the variance parameters. Columns of these matrices consist of the estimated parameters, the lower and upper bounds for the 95 percent confidencial intervals. It is returned if boot = TRUE
B0	List of Q matrices (K x iter) summarizing bootstrapped coefficients. The q-th matrix consists of the coefficients on the q-th quantile. Effective if boot = TRUE
S0	List of Q matrices (2 x iter) summarizing bootstrapped variance parameters. The q-th matrix consists of the parameters on the q-th quantile. Effective if boot = TRUE

Author(s)

Daisuke Murakami

References

Murakami, D. and Seya, H. (2017) Spatially filtered unconditional quantile regression. ArXiv.

See Also

plot_qr

Examples

```
require(spdep)
data(boston)
y <- boston.c[, "CMEDV" ]
x <- boston.c[,c("CRIM","ZN","INDUS", "CHAS", "NOX","RM", "AGE",
                       "DIS" ,"RAD", "TAX", "PTRATIO", "B", "LSTAT")]
coords  <- boston.c[,c("LON", "LAT")]
meig    <- meigen(coords=coords)
res     <- resf_qr(y=y,x=x,meig=meig, boot=FALSE)
res
plot_qr(res,1)     # Intercept
plot_qr(res,2)     # Coefficient on CRIM
plot_qr(res,1,"s") # spcomp_SE
plot_qr(res,2,"s") # spcomp_Moran.I/max(Moran.I)

###Not run
#res <- resf_qr(y=y,x=x,meig=meig, boot=TRUE)
#res
#plot_qr(res,1)     # Intercept + 95 percent confidence interval (CI)
#plot_qr(res,2)     # Coefficient on CRIM + 95 percent CI
#plot_qr(res,1,"s") # spcomp_SE + 95 percent CI
#plot_qr(res,2,"s") # spcomp_Moran.I/max(Moran.I) + 95 percent CI
```

---

resf_vc *Gaussian and non-Gaussian spatial regression models with varying coefficients*

Description

This model estimates regression coefficients, spatially varying coefficients (SVCs), non-spatially varying coefficients (NVC; coefficients varying with respect to explanatory variable value), SNVC (= SVC + NVC), group effects, and residual spatial dependence. The random-effects eigenvector spatial filtering, which is an approximate Gaussian process approach, is used for modeling the spatial process in coefficients and residuals. While the resf_vc function estimates a SVC model by default, the type of coefficients (constant, SVC, NVC, or SNVC) can be selected through a BIC/AIC minimization. The explained variables are transformed to fit the data distribution if nongauss is specified. Thus, this function is available for modeling Gaussian and non-Gaussian continuous data and count data (see nongauss_y).

Note that SNVCs can be mapped just like SVCs. SNVC model is more robust against spurious correlation (multicollinearity) and stable than SVC models (see Murakami and Griffith, 2020).

Usage

```
resf_vc(y, x, xconst = NULL, xgroup = NULL, weight = NULL, offset = NULL,
        x_nvc = FALSE, xconst_nvc = FALSE, x_sel = TRUE, x_nvc_sel = TRUE,
        xconst_nvc_sel = TRUE, nvc_num = 5, meig, method = "reml",
        penalty = "bic", maxiter = 30, nongauss = NULL )
```

Arguments

y	Vector of explained variables (N x 1)
x	Matrix of explanatory variables with spatially varying coefficients (SVC) (N x K)
xconst	Matrix of explanatory variables with constant coefficients (N x K_c). Default is NULL
xgroup	Matrix of group IDs. The IDs may be group numbers or group names (N x K_g). Default is NULL
weight	Vector of weights for samples (N x 1). When non-NULL, the adjusted R-squared value is evaluated for weighted explained variables. Default is NULL
offset	Vector of offset variables (N x 1). Available if y is count (y_type = "count" is specified in the nongauss_y function). Default is NULL
x_nvc	If TRUE, SNVCs are assumed on x. Otherwise, SVCs are assumed. Default is FALSE
xconst_nvc	If TRUE, NVCs are assumed on xconst. Otherwise, constant coefficients are assumed. Default is FALSE
x_sel	If TRUE, type of coefficient (SVC or constant) on x is selected through a BIC (default) or AIC minimization. If FALSE, SVCs are assumed across x. Alternatively, x_sel can be given by column number(s) of x. For example, if x_sel = 2, the coefficient on the second explanatory variable in x is SVC and the other coefficients are constants. The Default is TRUE
x_nvc_sel	If TRUE, type of coefficient (NVC or constant) on x is selected through the BIC (default) or AIC minimization. If FALSE, NVCs are assumed across x. Alternatively, x_nvc_sel can be given by column number(s) of x. For example, if x_nvc_sel = 2, the coefficient on the second explanatory variable in x is NVC and the other coefficients are constants. The Default is TRUE
xconst_nvc_sel	If TRUE, type of coefficient (NVC or constant) on xconst is selected through the BIC (default) or AIC minimization. If FALSE, NVCs are assumed across xconst. Alternatively, xconst_nvc_sel can be given by column number(s) of xconst. For example, if xconst_nvc_sel = 2, the coefficient on the second explanatory variable in xconst is NVC and the other coefficients are constants.The Default is TRUE

nvc_num: Number of basis functions used to model NVC. An intercept and nvc_num natural spline basis functions are used to model each NVC. Default is 5

meig: Moran eigenvectors and eigenvalues. Output from meigen or meigen_f

method: Estimation method. Restricted maximum likelihood method ("reml") and maximum likelihood method ("ml") are available. Default is "reml"

penalty: Penalty to select varying coefficients and stablize the estimates. The current options are "bic" for the Baysian information criterion-type penalty (N x log(K)) and "aic" for the Akaike information criterion (2K). Default is "bic"

maxiter: Maximum number of iterations. Default is 30

nongauss: Parameter setup for modeling non-Gaussian continuous and count data. Output from nongauss_y

Details

This function estimates Gaussian and non-Gaussian spatial model for continuous and count data. For non-Gaussian modeling, see nongauss_y.

Value

b_vc: Matrix of estimated spatially and non-spatially varying coefficients (SNVC = SVC + NVC) on x (N x K)

bse_vc: Matrix of standard errors for the SNVCs on x (N x k)

t_vc: Matrix of t-values for the SNVCs on x (N x K)

p_vc: Matrix of p-values for the SNVCs on x (N x K)

B_vc_s: List summarizing estimated SVCs (in SNVC) on x. The four elements are the SVCs (N x K), the standard errors (N x K), t-values (N x K), and p-values (N x K), respectively

B_vc_n: List summarizing estimated NVCs (in SNVC) on x. The four elements are the NVCs (N x K), the standard errors (N x K), t-values (N x K), and p-values (N x K), respectively

c: Matrix with columns for the estimated coefficients on xconst, their standard errors, t-values, and p-values (K_c x 4). Effective if xconst_nvc = FALSE

c_vc: Matrix of estimated NVCs on xconst (N x K_c). Effective if xconst_nvc = TRUE

cse_vc: Matrix of standard errors for the NVCs on xconst (N x k_c). Effective if xconst_nvc = TRUE

ct_vc: Matrix of t-values for the NVCs on xconst (N x K_c). Effective if xconst_nvc = TRUE

cp_vc: Matrix of p-values for the NVCs on xconst (N x K_c). Effective if xconst_nvc = TRUE

b_g: List of K_g matrices with columns for the estimated group effects, their standard errors, and t-values s — List of variance parameters in the SNVC (SVC + NVC) on x. The first element is a 2 x K matrix summarizing variance parameters for SVC. The (1, k)-th element is the standard error of the k-th SVC, while the (2, k)-th element is the Moran's I value is scaled to take a value between 0 (no spatial dependence) and 1 (strongest spatial dependence). Based on Griffith (2003), the scaled Moran'I value is interpretable as follows: 0.25-0.50:weak; 0.50-0.70:moderate; 0.70-0.90:strong; 0.90-1.00:marked. The second element of s is the vector of standard errors of the NVCs

s_c — Vector of standard errors of the NVCs on xconst

s_g — Vector of standard errors of the group effects

vc — List indicating whether SVC/NVC are removed or not during the BIC/AIC minimization. 1 indicates not removed (replaced with constant) whreas 0 indicates removed

e — Error statistics. When y_type="continuous", it includes residual standard error (resid_SE), adjusted conditional R2 (adjR2(cond)), restricted log-likelihood (rlogLik), Akaike information criterion (AIC), and Bayesian information criterion (BIC). rlogLik is replaced with log-likelihood (logLik) if method = "ml". resid_SE is replaced with the residual standard error for the transformed y (resid_SE_trans) if nongauss is specified. When y_type="count", the error statistics includes root mean squared error (RMSE), Gaussian likelihood approximating the model, AIC and BIC based on the likelihood, and the proportion of the null deviance explained by the model (deviance explained (%)). deviance explained, which is also used in the mgcv package, corresponds to the adjusted R2 in case of the linear regression

pred — Matrix of predicted values for y (pred) and their standard errors (pred_se) (N x 2). If y is transformed by specifying nongauss_y, the predicted values in the transformed/normalized scale are added as another column named pred_trans

pred_quantile — Matrix of the quantiles for the predicted values (N x 15). It is useful to evaluate uncertainty in the predictive value

tr_par — List of the parameter estimates for the tr_num SAL transformations. The k-th element of the list includes the four parameters for the k-th SAL transformation (see nongauss_y)

tr_bpar — The estimated parameter in the Box-Cox transformation

tr_y — Vector of the transformed explaied variables

resid — Vector of residuals (N x 1)

pdf — Matrix whose first column consists of evenly spaced values within the value range of y and the second column consists of the estimated value of the probability density function for y if y_type in nongauss_y is "continuous" and probability mass function if y_type = "count". If offset is specified (and y_type = "count"), the PMF given median offset value is evaluated

skew_kurt — Skewness and kurtosis of the estimated probability density/mass function of y

other — List of other outputs, which are internally used

Author(s)

Daisuke Murakami

References

Murakami, D., Yoshida, T., Seya, H., Griffith, D.A., and Yamagata, Y. (2017) A Moran coefficient-based mixed effects approach to investigate spatially varying relationships. Spatial Statistics, 19, 68-89.

Murakami, D., Kajita, M., Kajita, S. and Matsui, T. (2021) Compositionally-warped additive mixed modeling for a wide variety of non-Gaussian data. Spatial Statistics, 43, 100520.

Murakami, D., and Griffith, D.A. (2021) Balancing spatial and non-spatial variations in varying coefficient modeling: a remedy for spurious correlation. Geographical Analysis, DOI: 10.1111/gean.12310.

Griffith, D. A. (2003) Spatial autocorrelation and spatial filtering: gaining understanding through theory and scientific visualization. Springer Science & Business Media.

See Also

meigen, meigen_f, coef_marginal, besf_vc

Examples

```
require(spdep)
data(boston)
y       <- boston.c[, "CMEDV"]
x       <- boston.c[,c("CRIM", "AGE")]
xconst  <- boston.c[,c("ZN","DIS","RAD","NOX",  "TAX","RM", "PTRATIO", "B")]
xgroup  <- boston.c[,"TOWN"]
coords  <- boston.c[,c("LON", "LAT")]
meig    <- meigen(coords=coords)
# meig <- meigen_f(coords=coords)  ## for large samples

#####################################################
############## Gaussian SVC models ##################
#####################################################

#### SVC or constant coefficients on x ##############

res     <- resf_vc(y=y,x=x,xconst=xconst,meig=meig )
res
plot_s(res,0) # Spatially varying intercept
plot_s(res,1) # 1st SVC (Not shown because the SVC is estimated constant)
plot_s(res,2) # 2nd SVC

#### SVC on x #######################################

#res2   <- resf_vc(y=y,x=x,xconst=xconst,meig=meig, x_sel = FALSE )

#### Group-level SVC or constant coefficients on x ##
#### Group-wise random intercepts ###################

#meig_g <- meigen(coords, s_id=xgroup)
#res3   <- resf_vc(y=y,x=x,xconst=xconst,meig=meig_g,xgroup=xgroup)

#####################################################
```

```
############## Gaussian SNVC models #################
####################################################

#### SNVC, SVC, NVC, or constant coefficients on x ###

#res4   <- resf_vc(y=y,x=x,xconst=xconst,meig=meig, x_nvc =TRUE)

#### SNVC, SVC, NVC, or constant coefficients on x ###
#### NVC or Constant coefficients on xconst ##########

#res5   <- resf_vc(y=y,x=x,xconst=xconst,meig=meig, x_nvc =TRUE, xconst_nvc=TRUE)
#plot_s(res5,0)            # Spatially varying intercept
#plot_s(res5,1)            # Spatial plot of the SNVC (SVC + NVC) on x[,1]
#plot_s(res5,1,btype="svc")# Spatial plot of SVC in the SNVC
#plot_s(res5,1,btype="nvc")# Spatial plot of NVC in the SNVC
#plot_n(res5,1)            # 1D plot of the NVC

#plot_s(res5,6,xtype="xconst")# Spatial plot of the NVC on xconst[,6]
#plot_n(res5,6,xtype="xconst")# 1D plot of the NVC on xconst[,6]


####################################################
############## Non-Gaussian SVC models ##############
####################################################

#### Generalized model for continuous data ##########
# - Probability distribution is estimated from data

#ng6    <- nongauss_y( tr_num = 2 )# 2 SAL transformations to Gaussianize y
#res6   <- resf_vc(y=y,x=x,xconst=xconst,meig=meig, nongauss = ng6 )
#res6                   # tr_num may be selected by comparing BIC (or AIC)

#coef_marginal_vc(res6) # marginal effects from x (dy/dx)
#plot(res6$pdf,type="l") # Estimated probability density function
#res6$skew_kurt          # Skew and kurtosis of the estimated PDF
#res6$pred_quantile[1:2,]# predicted value by quantile


#### Generalized model for non-negative continuous data
# - Probability distribution is estimated from data

#ng7    <- nongauss_y( tr_num = 2, y_nonneg = TRUE )
#res7   <- resf_vc(y=y,x=x,xconst=xconst,meig=meig, nongauss = ng7 )
#coef_marginal_vc(res7)

#### Overdispersed Poisson model for count data #####
# - y is assumed as a count data

#ng8    <- nongauss_y( y_type = "count" )
#res8   <- resf_vc(y=y,x=x,xconst=xconst,meig=meig, nongauss = ng8 )

#### Generalized model for count data ###############
# - y is assumed as a count data
```

```
# - Probability distribution is estimated from data

#ng9    <- nongauss_y( y_type = "count", tr_num = 2 )
#res9   <- resf_vc(y=y,x=x,xconst=xconst,meig=meig, nongauss = ng9 )
```

---

weigen *Extract eigenvectors from a spatial weight matrix*

Description

This function extracts eigenvectors and eigenvalues from a spatial weight matrix.

Usage

```
weigen( x = NULL, type = "knn", k = 4, threshold = 0.25, enum = NULL )
```

Arguments

x	Matrix of spatial point coordinates (N x 2), ShapePolygons object (N spatial units), or an user-specified spatial weight matrix (N x N) (see Details)
type	Type of spatial weights. The currently available options are "knn" for the k-nearest neighbor-based weights, and "tri" for the Delaunay triangulation-based weights. If ShapePolygons are provided for x, type is ignored, and the rook-type neighborhood matrix is created
k	Number of nearest neighbors. It is used if type ="knn"
threshold	Threshold for the eigenvalues (scalar). Suppose that lambda_1 is the maximum eigenvalue. Then, this fucntion extracts eigenvectors whose corresponding eigenvalues are equal or greater than [threshold x lambda_1]. It must be a value between 0 and 1. Default is 0.25 (see Details)
enum	Optional. The muximum acceptable mumber of eigenvectors to be used for spatial modeling (scalar)

Details

If user-specified spatial weight matrix is provided for x, this function returns the eigen-pairs of the matrix. Otherwise, if a SpatialPolygons object is provided to x, the rook-type neighborhood matrix is created using this polygon, and eigen-decomposed. Otherwise, if point coordinats are provided to x, a spatial weight matrix is created according to type, and eigen-decomposed.

By default, the ARPACK routine is implemented for fast eigen-decomposition.

threshold = 0.25 (default) is a standard setting for topology-based ESF (see Tiefelsdorf and Griffith, 2007) while threshold = 0.00 is a usual setting for distance-based ESF.

Value

sf	Matrix of the first L eigenvectors (N x L)
ev	Vector of the first L eigenvalues (L x 1)
other	List of other outcomes, which are internally used

Author(s)

Daisuke Murakami

References

Tiefelsdorf, M. and Griffith, D.A. (2007) Semiparametric filtering of spatial autocorrelation: the eigenvector approach. Environment and Planning A, 39 (5), 1193-1221.

Murakami, D. and Griffith, D.A. (2018) Low rank spatial econometric models. Arxiv, 1810.02956.

See Also

meigen, meigen_f

Examples

```
require(spdep);library(rgdal)
data(boston)

########## Rook adjacency-based W
poly     <- readOGR(system.file("shapes/boston_tracts.shp",package="spData")[1])
weig1     <- weigen( poly )

########## knn-based W
coords    <- boston.c[,c("LON", "LAT")]
weig2     <- weigen( coords, type = "knn" )

########## Delaunay triangulation-based W
coords    <- boston.c[,c("LON", "LAT")]
weig3     <- weigen( coords, type = "tri")

########## User-specified W
dmat      <- as.matrix(dist(coords))
cmat      <- exp(-dmat)
diag(cmat)<- 0
weig4     <- weigen( cmat, threshold = 0 )
```

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