Package 'tidygraph'

August 22, 2022

Type Package

Title A Tidy API for Graph Manipulation

Version 1.2.2

Maintainer Thomas Lin Pedersen <thomasp85@gmail.com>

Description A graph, while not ``tidy'' in itself, can be thought of as two tidy
data frames describing node and edge data respectively. 'tidygraph'
provides an approach to manipulate these two virtual data frames using the
API defined in the 'dplyr' package, as well as provides tidy interfaces to
a lot of common graph algorithms.

License MIT + file LICENSE

Encoding UTF-8

RoxygenNote 7.2.1

Imports tibble, dplyr (>= 0.8.5), igraph, magrittr, utils, rlang, R6,
tools, stats, tidyr, pillar, cli

URL https://tidygraph.data-imaginist.com,

https://github.com/thomasp85/tidygraph

BugReports https://github.com/thomasp85/tidygraph/issues

LinkingTo cpp11

Suggests network, data.tree, ape, graph, methods, testthat, covr,
seriation, netrankr, influenceR, NetSwan

SystemRequirements C++11

NeedsCompilation yes

Author Thomas Lin Pedersen [cre, aut]
(<https://orcid.org/0000-0002-5147-4711>)

Repository CRAN

Date/Publication 2022-08-22 07:20:02 UTC

R topics documented:

---

activate   *Determine the context of subsequent manipulations*

Description

As a tbl_graph can be considered as a collection of two linked tables it is necessary to specify which
table is referenced during manipulations. The activate verb does just that and needs affects all
subsequent manipulations until a new table is activated. active is a simple query function to get the
currently acitve context. In addition to the use of activate it is also possible to activate nodes or
edges as part of the piping using the %N>% and %E>% pipes respectively. Do note that this approach
somewhat obscures what is going on and is thus only recommended for quick, one-line, fixes in
interactive use.

Usage

```
activate(.data, what)

active(x)

lhs %N>% rhs

lhs %E>% rhs
```

Arguments

.data, x, lhs	A tbl_graph or a grouped_tbl_graph
what	What should get activated? Possible values are nodes or edges.
rhs	A function to pipe into

Value

A tbl_graph

Note

Activate will ungroup a grouped_tbl_graph.

Examples

```
gr <- create_complete(5) %>%
  activate(nodes) %>%
  mutate(class = sample(c('a', 'b'), 5, TRUE)) %>%
  activate(edges) %>%
  arrange(from)

# The above could be achieved using the special pipes as well
gr <- create_complete(5) %N>%
  mutate(class = sample(c('a', 'b'), 5, TRUE)) %E>%
  arrange(from)
# But as you can see it obscures what part of the graph is being targeted
```

---

as_tbl_graph.data.frame
A data structure for tidy graph manipulation

Description

The `tbl_graph` class is a thin wrapper around an `igraph` object that provides methods for ma-
nipulating the graph using the tidy API. As it is just a subclass of `igraph` every igraph method
will work as expected. A grouped_tbl_graph is the equivalent of a grouped_df where either the
nodes or the edges has been grouped. The grouped_tbl_graph is not constructed directly but by
using the group_by() verb. After creation of a tbl_graph the nodes are activated by default. The
context can be changed using the activate() verb and affects all subsequent operations. Chang-
ing context automatically drops any grouping. The current active context can always be extracted
with as_tibble(), which drops the graph structure and just returns a tbl_df or a grouped_df de-
pending on the state of the tbl_graph. The returned context can be overriden by using the active
argument in as_tibble().

Usage

```
## S3 method for class 'data.frame'
as_tbl_graph(x, directed = TRUE, ...)

## S3 method for class 'Node'
as_tbl_graph(x, directed = TRUE, mode = "out", ...)

## S3 method for class 'dendrogram'
as_tbl_graph(x, directed = TRUE, mode = "out", ...)

## S3 method for class 'graphNEL'
as_tbl_graph(x, ...)

## S3 method for class 'graphAM'
as_tbl_graph(x, ...)

## S3 method for class 'graphBAM'
as_tbl_graph(x, ...)

## S3 method for class 'hclust'
as_tbl_graph(x, directed = TRUE, mode = "out", ...)

## S3 method for class 'igraph'
as_tbl_graph(x, ...)

## S3 method for class 'list'
as_tbl_graph(x, directed = TRUE, node_key = "name", ...)

## S3 method for class 'matrix'
as_tbl_graph(x, directed = TRUE, ...)

## S3 method for class 'network'
as_tbl_graph(x, ...)

## S3 method for class 'phylo'
```

```
as_tbl_graph(x, directed = NULL, ...)

## S3 method for class 'evonet'
as_tbl_graph(x, directed = TRUE, ...)

tbl_graph(nodes = NULL, edges = NULL, directed = TRUE, node_key = "name")

as_tbl_graph(x, ...)

## Default S3 method:
as_tbl_graph(x, ...)

is.tbl_graph(x)
```

Arguments

x	An object convertible to a `tbl_graph`
directed	Should the constructed graph be directed (defaults to `TRUE`)
...	Arguments passed on to the conversion function
mode	In case `directed = TRUE` should the edge direction be away from node or towards. Possible values are `"out"` (default) or `"in"`.
node_key	The name of the column in `nodes` that character represented `to` and `from` columns should be matched against. If `NA` the first column is always chosen. This setting has no effect if `to` and `from` are given as integers.
nodes	A `data.frame` containing information about the nodes in the graph. If `edges$to` and/or `edges$from` are characters then they will be matched to the column named according to `node_key` in nodes, if it exists. If not, they will be matched to the first column.
edges	A `data.frame` containing information about the edges in the graph. The terminal nodes of each edge must either be encoded in a `to` and `from` column, or in the two first columns, as integers. These integers refer to `nodes` index.

Details

Constructors are provided for most data structures that resembles networks. If a class provides an igraph::as.igraph() method it is automatically supported.

Value

A `tbl_graph` object

Functions

- `as_tbl_graph(data.frame)`: Method for edge table and set membership table
- `as_tbl_graph(Node)`: Method to deal with Node objects from the data.tree package
- `as_tbl_graph(dendrogram)`: Method for dendrogram objects

- `as_tbl_graph(graphNEL)`: Method for handling graphNEL objects from the graph package (on Bioconductor)

- `as_tbl_graph(graphAM)`: Method for handling graphAM objects from the graph package (on Bioconductor)

- `as_tbl_graph(graphBAM)`: Method for handling graphBAM objects from the graph package (on Bioconductor)

- `as_tbl_graph(hclust)`: Method for hclust objects

- `as_tbl_graph(igraph)`: Method for igraph object. Simply subclasses the object into a `tbl_graph`

- `as_tbl_graph(list)`: Method for adjacency lists and lists of node and edge tables

- `as_tbl_graph(matrix)`: Method for edgelist, adjacency and incidence matrices

- `as_tbl_graph(network)`: Method to handle network objects from the `network` package. Requires this packages to work.

- `as_tbl_graph(phylo)`: Method for handling phylo objects from the ape package

- `as_tbl_graph(evonet)`: Method for handling evonet objects from the ape package

- `as_tbl_graph(default)`: Default method. tries to call [`igraph::as.igraph()`](igraph::as.igraph()) on the input.

Examples

```
rstat_nodes <- data.frame(name = c("Hadley", "David", "Romain", "Julia"))
rstat_edges <- data.frame(from = c(1, 1, 1, 2, 3, 3, 4, 4, 4),
                            to = c(2, 3, 4, 1, 1, 2, 1, 2, 3))
tbl_graph(nodes = rstat_nodes, edges = rstat_edges)
```

---

bind_graphs	*Add graphs, nodes, or edges to a tbl_graph*

Description

These functions are tbl_graph pendants to [`dplyr::bind_rows()`](dplyr::bind_rows()) that allows you to grow your `tbl_graph` by adding rows to either the nodes data, the edges data, or both. As with `bind_rows()` columns are matched by name and are automatically filled with NA if the column doesn't exist in some instances. In the case of `bind_graphs()` the graphs are automatically converted to `tbl_graph` objects prior to binding. The edges in each graph will continue to reference the nodes in the graph where they originated, meaning that their terminal node indexes will be shifted to match the new index of the node in the combined graph. This means the `bind_graphs()` always result in a disconnected graph. See [`graph_join()`](graph_join()) for merging graphs on common nodes.

Usage

```
bind_graphs(.data, ...)

bind_nodes(.data, ...)

bind_edges(.data, ..., node_key = "name")
```

Arguments

`.data`	A `tbl_graph`, or a list of `tbl_graph` objects (for `bind_graphs()`).
`...`	In case of `bind_nodes()` and `bind_edges()` data.frames to add. In the case of `bind_graphs()` objects that are convertible to `tbl_graph` using `as_tbl_graph()`.
`node_key`	The name of the column in `nodes` that character represented `to` and `from` columns should be matched against. If `NA` the first column is always chosen. This setting has no effect if `to` and `from` are given as integers.

Value

A `tbl_graph` containing the new data

Examples

```
graph <- create_notable('bull')
new_graph <- create_notable('housex')

# Add nodes
graph %>% bind_nodes(data.frame(new = 1:4))

# Add edges
graph %>% bind_edges(data.frame(from = 1, to = 4:5))

# Add graphs
graph %>% bind_graphs(new_graph)
```

---

centrality   *Calculate node and edge centrality*

Description

The centrality of a node measures the importance of node in the network. As the concept of importance is ill-defined and dependent on the network and the questions under consideration, many centrality measures exist. `tidygraph` provides a consistent set of wrappers for all the centrality measures implemented in igraph for use inside [`dplyr::mutate()`](#) and other relevant verbs. All functions provided by `tidygraph` have a consistent naming scheme and automatically calls the function on the graph, returning a vector with measures ready to be added to the node data. Further `tidygraph` provides access to the `netrankr` engine for centrality calculations and define a number of centrality measures based on that, as well as provide a manual mode for specifying more-or-less any centrality score.

Usage

```
centrality_alpha(
  weights = NULL,
  alpha = 1,
```

```
  exo = 1,
  tol = 1e-07,
  loops = FALSE
)

centrality_authority(
  weights = NULL,
  scale = TRUE,
  options = igraph::arpack_defaults
)

centrality_betweenness(
  weights = NULL,
  directed = TRUE,
  cutoff = NULL,
  nobigint = TRUE,
  normalized = FALSE
)

centrality_power(exponent = 1, rescale = FALSE, tol = 1e-07, loops = FALSE)

centrality_closeness(
  weights = NULL,
  mode = "out",
  normalized = FALSE,
  cutoff = NULL
)

centrality_eigen(
  weights = NULL,
  directed = FALSE,
  scale = TRUE,
  options = igraph::arpack_defaults
)

centrality_hub(weights = NULL, scale = TRUE, options = igraph::arpack_defaults)

centrality_pagerank(
  weights = NULL,
  directed = TRUE,
  damping = 0.85,
  personalized = NULL
)

centrality_subgraph(loops = FALSE)

centrality_degree(
  weights = NULL,
```

```
  mode = "out",
  loops = TRUE,
  normalized = FALSE
)

centrality_edge_betweenness(weights = NULL, directed = TRUE, cutoff = NULL)

centrality_manual(relation = "dist_sp", aggregation = "sum", ...)

centrality_closeness_harmonic()

centrality_closeness_residual()

centrality_closeness_generalised(alpha)

centrality_integration()

centrality_communicability()

centrality_communicability_odd()

centrality_communicability_even()

centrality_subgraph_odd()

centrality_subgraph_even()

centrality_katz(alpha = NULL)

centrality_betweenness_network(netflowmode = "raw")

centrality_betweenness_current()

centrality_betweenness_communicability()

centrality_betweenness_rsp_simple(rspxparam = 1)

centrality_betweenness_rsp_net(rspxparam = 1)

centrality_information()

centrality_decay(alpha = 1)

centrality_random_walk()

centrality_expected()
```

Arguments

`weights`	The weight of the edges to use for the calculation. Will be evaluated in the context of the edge data.
`alpha`	Relative importance of endogenous vs exogenous factors (`centrality_alpha`), the exponent to the power transformation of the distance metric (`centrality_closeness_generalised`), the base of power transformation (`centrality_decay`), or the attenuation factor (`centrality_katz`)
`exo`	The exogenous factors of the nodes. Either a scalar or a number number for each node. Evaluated in the context of the node data.
`tol`	Tolerance for near-singularities during matrix inversion
`loops`	Should loops be included in the calculation
`scale`	Should the output be scaled between 0 and 1
`options`	Settings passed on to `igraph::arpack()`
`directed`	Should direction of edges be used for the calculations
`cutoff`	maximum path length to use during calculations
`nobigint`	Should big integers be avoided during calculations
`normalized`	Should the output be normalized
`exponent`	The decay rate for the Bonacich power centrality
`rescale`	Should the output be scaled to sum up to 1
`mode`	How should edges be followed. Ignored for undirected graphs
`damping`	The damping factor of the page rank algorithm
`personalized`	The probability of jumping to a node when abandoning a random walk. Evaluated in the context of the node data.
`relation`	The indirect relation measure type to be used in `netrankr::indirect_relations`
`aggregation`	The aggregation type to use on the indirect relations to be used in `netrankr::aggregate_positions`
`...`	Arguments to pass on to `netrankr::indirect_relations`
`netflowmode`	The return type of the network flow distance, either `'raw'` or `'frac'`
`rspxparam`	inverse temperature parameter

Value

A numeric vector giving the centrality measure of each node.

Functions

- `centrality_alpha()`: Wrapper for igraph::alpha_centrality()
- `centrality_authority()`: Wrapper for igraph::authority_score()
- `centrality_betweenness()`: Wrapper for igraph::betweenness() and igraph::estimate_betweenness()
- `centrality_power()`: Wrapper for igraph::power_centrality()
- `centrality_closeness()`: Wrapper for igraph::closeness() and igraph::estimate_closeness()
- `centrality_eigen()`: Wrapper for igraph::eigen_centrality()

- centrality_hub(): Wrapper for `igraph::hub_score()`

- centrality_pagerank(): Wrapper for `igraph::page_rank()`

- centrality_subgraph(): Wrapper for `igraph::subgraph_centrality()`

- centrality_degree(): Wrapper for `igraph::degree()` and `igraph::strength()`

- centrality_edge_betweenness(): Wrapper for `igraph::edge_betweenness()`

- centrality_manual(): Manually specify your centrality score using the `netrankr` framework (netrankr)

- centrality_closeness_harmonic(): centrality based on inverse shortest path (netrankr)

- centrality_closeness_residual(): centrality based on 2-to-the-power-of negative shortest path (netrankr)

- centrality_closeness_generalised(): centrality based on alpha-to-the-power-of negative shortest path (netrankr)

- centrality_integration(): centrality based on $1 - (x - 1)/max(x)$ transformation of shortest path (netrankr)

- centrality_communicability(): centrality an exponential tranformation of walk counts (netrankr)

- centrality_communicability_odd(): centrality an exponential tranformation of odd walk counts (netrankr)

- centrality_communicability_even(): centrality an exponential tranformation of even walk counts (netrankr)

- centrality_subgraph_odd(): subgraph centrality based on odd walk counts (netrankr)

- centrality_subgraph_even(): subgraph centrality based on even walk counts (netrankr)

- centrality_katz(): centrality based on walks penalizing distant nodes (netrankr)

- centrality_betweenness_network(): Betweenness centrality based on network flow (netrankr)

- centrality_betweenness_current(): Betweenness centrality based on current flow (netrankr)

- centrality_betweenness_communicability(): Betweenness centrality based on communicability (netrankr)

- centrality_betweenness_rsp_simple(): Betweenness centrality based on simple randomised shortest path dependencies (netrankr)

- centrality_betweenness_rsp_net(): Betweenness centrality based on net randomised shortest path dependencies (netrankr)

- centrality_information(): centrality based on inverse sum of resistance distance between nodes (netrankr)

- centrality_decay(): based on a power transformation of the shortest path (netrankr)

- centrality_random_walk(): centrality based on the inverse sum of expected random walk length between nodes (netrankr)

- centrality_expected(): Expected centrality ranking based on exact rank probability (netrankr)

Examples

```
create_notable('bull') %>%
  activate(nodes) %>%
  mutate(importance = centrality_alpha())

# Most centrality measures are for nodes but not all
create_notable('bull') %>%
  activate(edges) %>%
  mutate(importance = centrality_edge_betweenness())
```

---

component_games   *Graph games based on connected components*

Description

This set of graph creation algorithms simulate the topology by, in some way, connecting subgraphs.
The nature of their algorithm is described in detail at the linked igraph documentation.

Usage

```
play_blocks(n, size_blocks, p_between, directed = TRUE, loops = FALSE)

play_blocks_hierarchy(n, size_blocks, rho, p_within, p_between)

play_islands(n_islands, size_islands, p_within, m_between)

play_smallworld(
  n_dim,
  dim_size,
  order,
  p_rewire,
  loops = FALSE,
  multiple = FALSE
)
```

Arguments

n	The number of nodes in the graph.
size_blocks	The number of vertices in each block
p_between, p_within	
	The probability of edges within and between groups/blocks
directed	Should the resulting graph be directed
loops	Are loop edges allowed
rho	The fraction of vertices per cluster
n_islands	The number of densely connected islands

size_islands	The number of nodes in each island
m_between	The number of edges between groups/islands
n_dim, dim_size	
	The dimension and size of the starting lattice
order	The neighborhood size to create connections from
p_rewire	The rewiring probability of edges
multiple	Are multiple edges allowed

Value

A tbl_graph object

Functions

- play_blocks(): Create graphs by sampling from stochastic block model. See igraph::sample_sbm()
- play_blocks_hierarchy(): Create graphs by sampling from the hierarchical stochastic block model. See igraph::sample_hierarchical_sbm()
- play_islands(): Create graphs with fixed size and edge probability of subgraphs as well as fixed edge count between subgraphs. See igraph::sample_islands()
- play_smallworld(): Create graphs based on the Watts-Strogatz small- world model. See igraph::sample_smallworld()

See Also

Other graph games: evolution_games, sampling_games, type_games

Examples

```
plot(play_islands(4, 10, 0.7, 3))
```

---

context_accessors   *Access graph, nodes, and edges directly inside verbs*

Description

These three functions makes it possible to directly access either the node data, the edge data or the graph itself while computing inside verbs. It is e.g. possible to add an attribute from the node data to the edges based on the terminating nodes of the edge, or extract some statistics from the graph itself to use in computations.

Usage

```
.G()

.N()

.E()
```

Value

Either a `tbl_graph` (`.G()`) or a `tibble` (`.N()`)

Functions

- `.G()`: Get the tbl_graph you're currently working on
- `.N()`: Get the nodes data from the graph you're currently working on
- `.E()`: Get the edges data from the graph you're currently working on

Examples

```
# Get data from the nodes while computing for the edges
create_notable('bull') %>%
  activate(nodes) %>%
  mutate(centrality = centrality_power()) %>%
  activate(edges) %>%
  mutate(mean_centrality = (.N()$centrality[from] + .N()$centrality[to])/2)
```

---

create_graphs   *Create different types of well-defined graphs*

Description

These functions creates a long list of different types of well-defined graphs, that is, their structure is not based on any randomisation. All of these functions are shallow wrappers around a range of `igraph::make_*` functions but returns `tbl_graph` rather than `igraph` objects.

Usage

```
create_ring(n, directed = FALSE, mutual = FALSE)

create_path(n, directed = FALSE, mutual = FALSE)

create_chordal_ring(n, w)

create_de_bruijn(alphabet_size, label_size)

create_empty(n, directed = FALSE)

create_bipartite(n1, n2, directed = FALSE, mode = "out")

create_citation(n)

create_complete(n)

create_notable(name)
```

```
create_kautz(alphabet_size, label_size)

create_lattice(dim, directed = FALSE, mutual = FALSE, circular = FALSE)

create_star(n, directed = FALSE, mutual = FALSE, mode = "out")

create_tree(n, children, directed = TRUE, mode = "out")
```

Arguments

n, n1, n2	The number of nodes in the graph
directed	Should the graph be directed
mutual	Should mutual edges be created in case of the graph being directed
w	A matrix specifying the additional edges in the chordan ring. See `igraph::make_chordal_ring()`
alphabet_size	The number of unique letters in the alphabet used for the graph
label_size	The number of characters in each node
mode	In case of a directed, non-mutual, graph should the edges flow `'out'` or `'in'`
name	The name of a notable graph. See a complete list in `igraph::make_graph()`
dim	The dimensions of the lattice
circular	Should each dimension in the lattice wrap around
children	The number of children each node has in the tree (if possible)

Value

A tbl_graph

Functions

- `create_ring()`: Create a simple ring graph
- `create_path()`: Create a simple path
- `create_chordal_ring()`: Create a chordal ring
- `create_de_bruijn()`: Create a de Bruijn graph with the specified alphabet and label size
- `create_empty()`: Create a graph with no edges
- `create_bipartite()`: Create a full bipartite graph
- `create_citation()`: Create a full citation graph
- `create_complete()`: Create a complete graph (a graph where all nodes are connected)
- `create_notable()`: Create a graph based on its name. See `igraph::make_graph()`
- `create_kautz()`: Create a Kautz graph with the specified alphabet and label size
- `create_lattice()`: Create a multidimensional grid of nodes
- `create_star()`: Create a star graph (A single node in the center connected to all other nodes)
- `create_tree()`: Create a tree graph

Examples

```
# Create a complete graph with 10 nodes
create_complete(10)
```

---

edge_types   *Querying edge types*

Description

These functions lets the user query whether the edges in a graph is of a specific type. All functions return a logical vector giving whether each edge in the graph corresponds to the specific type.

Usage

```
edge_is_multiple()

edge_is_loop()

edge_is_mutual()

edge_is_from(from)

edge_is_to(to)

edge_is_between(from, to, ignore_dir = !graph_is_directed())

edge_is_incident(i)
```

Arguments

from, to, i	A vector giving node indices
ignore_dir	Is both directions of the edge allowed

Value

A logical vector of the same length as the number of edges in the graph

Functions

- edge_is_multiple(): Query whether each edge has any parallel siblings
- edge_is_loop(): Query whether each edge is a loop
- edge_is_mutual(): Query whether each edge has a sibling going in the reverse direction
- edge_is_from(): Query whether an edge goes from a set of nodes
- edge_is_to(): Query whether an edge goes to a set of nodes
- edge_is_between(): Query whether an edge goes between two sets of nodes
- edge_is_incident(): Query whether an edge goes from or to a set of nodes

Examples

```
create_star(10, directed = TRUE, mutual = TRUE) %>%
  activate(edges) %>%
  sample_frac(0.7) %>%
  mutate(single_edge = !edge_is_mutual())
```

---

evolution_games	*Graph games based on evolution*

Description

This games create graphs through different types of evolutionary mechanisms (not necessarily in a biological sense). The nature of their algorithm is described in detail at the linked igraph documentation.

Usage

```
play_citation_age(
  n,
  growth = 1,
  bins = n/7100,
  p_pref = (1:(bins + 1))^-3,
  directed = TRUE
)

play_forestfire(
  n,
  p_forward,
  p_backward = p_forward,
  growth = 1,
  directed = TRUE
)

play_growing(n, growth = 1, directed = TRUE, citation = FALSE)

play_barabasi_albert(
  n,
  power,
  growth = 1,
  growth_dist = NULL,
  use_out = FALSE,
  appeal_zero = 1,
  directed = TRUE,
  method = "psumtree"
)

play_barabasi_albert_aging(
```

```
  n,
  power,
  power_age,
  growth = 1,
  growth_dist = NULL,
  bins = 300,
  use_out = FALSE,
  appeal_zero = 1,
  appeal_zero_age = 0,
  directed = TRUE,
  coefficient = 1,
  coefficient_age = 1,
  window = NULL
)
```

Arguments

n	The number of nodes in the graph.
growth	The number of edges added at each iteration
bins	The number of aging bins
p_pref	The probability that an edge will be made to an age bin.
directed	Should the resulting graph be directed
p_forward, p_backward	
	Forward and backward burning probability
citation	Should a citation graph be created
power	The power of the preferential attachment
growth_dist	The distribution of the number of added edges at each iteration
use_out	Should outbound edges be used for calculating citation probability
appeal_zero	The appeal value for unconnected nodes
method	The algorithm to use for graph creation. Either 'psumtree', 'psumtree-multiple', or 'bag'
power_age	The aging exponent
appeal_zero_age	
	The appeal value of nodes without age
coefficient	The coefficient of the degree dependent part of attrictiveness
coefficient_age	
	The coefficient of the age dependent part of attrictiveness
window	The aging window to take into account when calculating the preferential attraction

Value

A tbl_graph object

Functions

- play_citation_age(): Create citation graphs based on a specific age link probability. See
  igraph::sample_last_cit()

- play_forestfire(): Create graphs by simulating the spead of fire in a forest. See igraph::sample_forestfire()

- play_growing(): Create graphs by adding a fixed number of edges at each iteration. See
  igraph::sample_growing()

- play_barabasi_albert(): Create graphs based on the Barabasi-Alberts preferential attach-
  ment model. See igraph::sample_pa()

- play_barabasi_albert_aging(): Create graphs based on the Barabasi-Alberts preferential
  attachment model, incoorporating node age preferrence. See igraph::sample_pa_age().

See Also

play_traits() and play_citation_type() for an evolutionary algorithm based on different node
types

Other graph games: component_games, sampling_games, type_games

Examples

```
plot(play_forestfire(50, 0.5))
```

---

graph_join   *Join graphs on common nodes*

Description

This graph-specific join method makes a full join on the nodes data and updates the edges in the
joining graph so they matches the new indexes of the nodes in the resulting graph. Node and edge
data is combined using dplyr::bind_rows() semantic, meaning that data is matched by column
name and filled with NA if it is missing in either of the graphs.

Usage

```
graph_join(x, y, by = NULL, copy = FALSE, suffix = c(".x", ".y"), ...)
```

Arguments

x	A tbl_graph
y	An object convertible to a tbl_graph using as_tbl_graph()
by	A character vector of variables to join by.
	If NULL, the default, *_join() will perform a natural join, using all variables in common across x and y. A message lists the variables so that you can check they're correct; suppress the message by supplying by explicitly.

> To join by different variables on x and y, use a named vector. For example, by =
> c("a" = "b") will match x$a to y$b.
>
> To join by multiple variables, use a vector with length > 1. For example, by
> = c("a", "b") will match x$a to y$a and x$b to y$b. Use a named vector
> to match different variables in x and y. For example, by = c("a" = "b", "c" =
> "d") will match x$a to y$b and x$c to y$d.
>
> To perform a cross-join, generating all combinations of x and y, use by = character().

copy   If x and y are not from the same data source, and copy is TRUE, then y will be
                  copied into the same src as x. This allows you to join tables across srcs, but it is
                  a potentially expensive operation so you must opt into it.

suffix   If there are non-joined duplicate variables in x and y, these suffixes will be added
                  to the output to disambiguate them. Should be a character vector of length 2.

...   Other parameters passed onto methods.

Value

A `tbl_graph` containing the merged graph

Examples

```
gr1 <- create_notable('bull') %>%
  activate(nodes) %>%
  mutate(name = letters[1:5])
gr2 <- create_ring(10) %>%
  activate(nodes) %>%
  mutate(name = letters[4:13])

gr1 %>% graph_join(gr2)
```

---

graph_measures   *Graph measurements*

Description

This set of functions provide wrappers to a number of ìgraphs graph statistic algorithms. As for
the other wrappers provided, they are intended for use inside the `tidygraph` framework and it is
thus not necessary to supply the graph being computed on as the context is known. All of these
functions are guarantied to return scalars making it easy to compute with them.

Usage

```
graph_adhesion()

graph_assortativity(attr, in_attr = NULL, directed = TRUE)

graph_automorphisms(sh = "fm")
```

```
graph_clique_num()

graph_clique_count(min = NULL, max = NULL, subset = NULL)

graph_component_count(type = "weak")

graph_motif_count(size = 3, cut.prob = rep(0, size))

graph_diameter(weights = NULL, directed = TRUE, unconnected = TRUE)

graph_girth()

graph_radius(mode = "out")

graph_mutual_count()

graph_asym_count()

graph_unconn_count()

graph_size()

graph_order()

graph_reciprocity(ignore_loops = TRUE, ratio = FALSE)

graph_min_cut(capacity = NULL)

graph_mean_dist(directed = TRUE, unconnected = TRUE)

graph_modularity(group, weights = NULL)
```

Arguments

`attr`	The node attribute to measure on
`in_attr`	An alternative node attribute to use for incomming node. If NULL the attribute given by `type` will be used
`directed`	Should a directed graph be treated as directed
`sh`	The splitting heuristics for the BLISS algorithm. Possible values are: 'f': first non-singleton cell, 'fl': first largest non-singleton cell, 'fs': first smallest non-singleton cell, 'fm': first maximally non-trivially connected non-singleton cell, 'flm': first largest maximally non-trivially connected non-singleton cell, 'fsm': first smallest maximally non-trivially connected non-singleton cell.
`min, max`	The upper and lower bounds of the cliques to be considered.
`subset`	The indexes of the nodes to start the search from (logical or integer). If provided only the cliques containing these nodes will be counted.
`type`	The type of component to count, either 'weak' or 'strong'. Ignored for undirected graphs.

size	The size of the motif.
cut.prob	Numeric vector giving the probabilities that the search graph is cut at a certain level. Its length should be the same as the size of the motif (the `size` argument). By default no cuts are made.
weights	Optional positive weight vector for calculating weighted distances. If the graph has a `weight` edge attribute, then this is used by default.
unconnected	Logical, what to do if the graph is unconnected. If FALSE, the function will return a number that is one larger the largest possible diameter, which is always the number of vertices. If TRUE, the diameters of the connected components will be calculated and the largest one will be returned.
mode	How should eccentricity be calculated. If `"out"` only outbound edges are followed. If `"in"` only inbound are followed. If `"all"` all edges are followed. Ignored for undirected graphs.
ignore_loops	Logical. Should loops be ignored while calculating the reciprocity
ratio	Should the old "ratio" approach from igraph < v0.6 be used
capacity	The capacity of the edges
group	The node grouping to calculate the modularity on

Value

A scalar, the type depending on the function

Functions

- graph_adhesion(): Gives the minimum edge connectivity. Wraps `igraph::edge_connectivity()`
- graph_assortativity(): Measures the propensity of similar nodes to be connected. Wraps `igraph::assortativity()`
- graph_automorphisms(): Calculate the number of automorphisms of the graph. Wraps `igraph::automorphisms()`
- graph_clique_num(): Get the size of the largest clique. Wraps `igraph::clique_num()`
- graph_clique_count(): Get the number of maximal cliques in the graph. Wraps `igraph::count_max_cliques()`
- graph_component_count(): Count the number of unconnected componenets in the graph. Wraps `igraph::count_components()`
- graph_motif_count(): Count the number of motifs in a graph. Wraps `igraph::count_motifs()`
- graph_diameter(): Measures the length of the longest geodesic. Wraps `igraph::diameter()`
- graph_girth(): Measrues the length of the shortest circle in the graph. Wraps `igraph::girth()`
- graph_radius(): Measures the smallest eccentricity in the graph. Wraps `igraph::radius()`
- graph_mutual_count(): Counts the number of mutually connected nodes. Wraps `igraph::dyad_census()`
- graph_asym_count(): Counts the number of asymmetrically connected nodes. Wraps `igraph::dyad_census()`
- graph_unconn_count(): Counts the number of unconnected node pairs. Wraps `igraph::dyad_census()`
- graph_size(): Counts the number of edges in the graph. Wraps `igraph::gsize()`
- graph_order(): Counts the number of nodes in the graph. Wraps `igraph::gorder()`

- graph_reciprocity(): Measures the proportion of mutual connections in the graph. Wraps igraph::reciprocity()
- graph_min_cut(): Calculates the minimum number of edges to remove in order to split the graph into two clusters. Wraps igraph::min_cut()
- graph_mean_dist(): Calculates the mean distance between all node pairs in the graph. Wraps igraph::mean_distance()
- graph_modularity(): Calculates the modularity of the graph contingent on a provided node grouping

Examples

```
# Use e.g. to modify computations on nodes and edges
create_notable('meredith') %>%
  activate(nodes) %>%
  mutate(rel_neighbors = centrality_degree()/graph_order())
```

---

graph_types   *Querying graph types*

Description

This set of functions lets the user query different aspects of the graph itself. They are all concerned with wether the graph implements certain properties and will all return a logical scalar.

Usage

```
graph_is_simple()

graph_is_directed()

graph_is_bipartite()

graph_is_connected()

graph_is_tree()

graph_is_forest()

graph_is_dag()

graph_is_chordal()

graph_is_complete()

graph_is_isomorphic_to(graph, method = "auto", ...)

graph_is_subgraph_isomorphic_to(graph, method = "auto", ...)
```

Arguments

`graph`	The graph to compare structure to
`method`	The algorithm to use for comparison
`...`	Arguments passed on to the comparison methods. See `igraph::is_isomorphic_to()` and `igraph::is_subgraph_isomorphic_to()`

Value

A logical scalar

Functions

- `graph_is_simple()`: Is the graph simple (no parallel edges)
- `graph_is_directed()`: Is the graph directed
- `graph_is_bipartite()`: Is the graph bipartite
- `graph_is_connected()`: Is the graph connected
- `graph_is_tree()`: Is the graph a tree
- `graph_is_forest()`: Is the graph an ensemble of multiple trees
- `graph_is_dag()`: Is the graph a directed acyclic graph
- `graph_is_chordal()`: Is the graph chordal
- `graph_is_complete()`: Is the graph fully connected
- `graph_is_isomorphic_to()`: Is the graph isomorphic to another graph. See `igraph::is_isomorphic_to()`
- `graph_is_subgraph_isomorphic_to()`: Is the graph an isomorphic subgraph to another graph. see `igraph::is_subgraph_isomorphic_to()`

Examples

```
gr <- create_tree(50, 4)

with_graph(gr, graph_is_tree())
```

---

group_graph	*Group nodes and edges based on community structure*

Description

These functions are wrappers around the various clustering functions provided by `igraph`. As with the other wrappers they automatically use the graph that is being computed on, and otherwise passes on its arguments to the relevant clustering function. The return value is always a numeric vector of group memberships so that nodes or edges with the same number are part of the same group. Grouping is predominantly made on nodes and currently the only grouping of edges supported is biconnected components.

Usage

```
group_components(type = "weak")

group_edge_betweenness(weights = NULL, directed = TRUE, n_groups = NULL)

group_fast_greedy(weights = NULL, n_groups = NULL)

group_infomap(weights = NULL, node_weights = NULL, trials = 10)

group_label_prop(weights = NULL, label = NULL, fixed = NULL)

group_leading_eigen(
  weights = NULL,
  steps = -1,
  label = NULL,
  options = igraph::arpack_defaults,
  n_groups = NULL
)

group_louvain(weights = NULL)

group_optimal(weights = NULL)

group_spinglass(weights = NULL, ...)

group_walktrap(weights = NULL, steps = 4, n_groups = NULL)

group_biconnected_component()
```

Arguments

type	The type of component to find. Either 'weak' or 'strong'
weights	The weight of the edges to use for the calculation. Will be evaluated in the context of the edge data.
directed	Should direction of edges be used for the calculations
n_groups	Integer scalar, the desired number of communities. If too low or two high, then an error message is given.
node_weights	The weight of the nodes to use for the calculation. Will be evaluated in the context of the node data.
trials	Number of times partition of the network should be attempted
label	The initial groups of the nodes. Will be evaluated in the context of the node data.
fixed	A logical vector determining which nodes should keep their initial groups. Will be evaluated in the context of the node data.
steps	The number of steps in the random walks
options	Settings passed on to igraph::arpack()
...	arguments passed on to igraph::cluster_spinglass()

Value

a numeric vector with the membership for each node in the graph. The enumeration happens in order based on group size progressing from the largest to the smallest group

Functions

- group_components(): Group by connected compenents using igraph::components()
- group_edge_betweenness(): Group densely connected nodes using igraph::cluster_edge_betweenness()
- group_fast_greedy(): Group nodes by optimising modularity using igraph::cluster_fast_greedy()
- group_infomap(): Group nodes by minimizing description length using igraph::cluster_infomap()
- group_label_prop(): Group nodes by propagating labels using igraph::cluster_label_prop()
- group_leading_eigen(): Group nodes based on the leading eigenvector of the modularity matrix using igraph::cluster_leading_eigen()
- group_louvain(): Group nodes by multilevel optimisation of modularity using igraph::cluster_louvain()
- group_optimal(): Group nodes by optimising the moldularity score using igraph::cluster_optimal()
- group_spinglass(): Group nodes using simulated annealing with igraph::cluster_spinglass()
- group_walktrap(): Group nodes via short random walks using igraph::cluster_walktrap()
- group_biconnected_component(): Group edges by their membership of the maximal binconnected components using igraph::biconnected_components()

Examples

```
create_notable('tutte') %>%
  activate(nodes) %>%
  mutate(group = group_infomap())
```

---

local_graph   *Measures based on the neighborhood of each node*

Description

These functions wraps a set of functions that all measures quantities of the local neighborhood of each node. They all return a vector or list matching the node position.

Usage

```
local_size(order = 1, mode = "all", mindist = 0)

local_members(order = 1, mode = "all", mindist = 0)

local_triangles()

local_ave_degree(weights = NULL)

local_transitivity(weights = NULL)
```

Arguments

order	Integer giving the order of the neighborhood.
mode	Character constant, it specifies how to use the direction of the edges if a directed graph is analyzed. For 'out' only the outgoing edges are followed, so all vertices reachable from the source vertex in at most order steps are counted. For '"in"' all vertices from which the source vertex is reachable in at most order steps are counted. '"all"' ignores the direction of the edges. This argument is ignored for undirected graphs.
mindist	The minimum distance to include the vertex in the result.
weights	An edge weight vector. For local_ave_degree: If this argument is given, the average vertex strength is calculated instead of vertex degree. For local_transitivity: if given weighted transitivity using the approach by *A. Barrat* will be calculated.

Value

A numeric vector or a list (for local_members) with elements corresponding to the nodes in the graph.

Functions

- local_size(): The size of the neighborhood in a given distance from the node. (Note that the node itself is included unless mindist > 0). Wraps igraph::ego_size().

- local_members(): The members of the neighborhood of each node in a given distance. Wraps igraph::ego().

- local_triangles(): The number of triangles each node participate in. Wraps igraph::count_triangles().

- local_ave_degree(): Calculates the average degree based on the neighborhood of each node. Wraps igraph::knn().

- local_transitivity(): Calculate the transitivity of each node, that is, the propensity for the nodes neighbors to be connected. Wraps igraph::transitivity()

Examples

```
# Get all neighbors of each graph
create_notable('chvatal') %>%
  activate(nodes) %>%
  mutate(neighborhood = local_members(mindist = 1))

# These are equivalent
create_notable('chvatal') %>%
  activate(nodes) %>%
  mutate(n_neighbors = local_size(mindist = 1),
         degree = centrality_degree()) %>%
  as_tibble()
```

---

map_bfs   *Apply a function to nodes in the order of a breath first search*

Description

These functions allow you to map over the nodes in a graph, by first performing a breath first search on the graph and then mapping over each node in the order they are visited. The mapping function will have access to the result and search statistics for all the nodes between itself and the root in the search. To map over the nodes in the reverse direction use `map_bfs_back()`.

Usage

```
map_bfs(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_lgl(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_chr(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_int(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_dbl(root, mode = "out", unreachable = FALSE, .f, ...)
```

Arguments

root	The node to start the search from
mode	How should edges be followed? `'out'` only follows outbound edges, `'in'` only follows inbound edges, and `'all'` follows all edges. This parameter is ignored for undirected graphs.
unreachable	Should the search jump to an unvisited node if the search is completed without visiting all nodes.
.f	A function to map over all nodes. See Details
...	Additional parameters to pass to `.f`

Details

The function provided to `.f` will be called with the following arguments in addition to those supplied through `...`:

- graph: The full `tbl_graph` object
- node: The index of the node currently mapped over
- rank: The rank of the node in the search
- parent: The index of the node that led to the current node
- before: The index of the node that was visited before the current node
- after: The index of the node that was visited after the current node.

- `dist`: The distance of the current node from the root
- `path`: A table containing `node`, `rank`, `parent`, `before`, `after`, `dist`, and `result` columns giving the values for each node leading to the current node. The `result` column will contain the result of the mapping of each node in a list.

Instead of spelling out all of these in the function it is possible to simply name the ones needed and use `...` to catch the rest.

Value

`map_bfs()` returns a list of the same length as the number of nodes in the graph, in the order matching the node order in the graph (that is, not in the order they are called). `map_bfs_*()` tries to coerce its result into a vector of the classes `logical` (map_bfs_lgl), `character` (map_bfs_chr), `integer` (map_bfs_int), or `double` (map_bfs_dbl). These functions will throw an error if they are unsuccesful, so they are type safe.

See Also

Other node map functions: [map_bfs_back()](#), [map_dfs_back()](#), [map_dfs()](#)

Examples

```
# Accumulate values along a search
create_tree(40, children = 3, directed = TRUE) %>%
  mutate(value = round(runif(40)*100)) %>%
  mutate(value_acc = map_bfs_dbl(node_is_root(), .f = function(node, path, ...) {
    sum(.N()$value[c(node, path$node)])
  }))
```

---

map_bfs_back   *Apply a function to nodes in the reverse order of a breath first search*

Description

These functions allow you to map over the nodes in a graph, by first performing a breath first search on the graph and then mapping over each node in the reverse order they are visited. The mapping function will have access to the result and search statistics for all the nodes following itself in the search. To map over the nodes in the original direction use [map_bfs()](#).

Usage

```
map_bfs_back(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_back_lgl(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_back_chr(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_back_int(root, mode = "out", unreachable = FALSE, .f, ...)

map_bfs_back_dbl(root, mode = "out", unreachable = FALSE, .f, ...)
```

Arguments

`root`	The node to start the search from
`mode`	How should edges be followed? `'out'` only follows outbound edges, `'in'` only follows inbound edges, and `'all'` follows all edges. This parameter is ignored for undirected graphs.
`unreachable`	Should the search jump to an unvisited node if the search is completed without visiting all nodes.
`.f`	A function to map over all nodes. See Details
`...`	Additional parameters to pass to `.f`

Details

The function provided to `.f` will be called with the following arguments in addition to those supplied through `...`:

- `graph`: The full `tbl_graph` object

- `node`: The index of the node currently mapped over

- `rank`: The rank of the node in the search

- `parent`: The index of the node that led to the current node

- `before`: The index of the node that was visited before the current node

- `after`: The index of the node that was visited after the current node.

- `dist`: The distance of the current node from the root

- `path`: A table containing `node`, `rank`, `parent`, `before`, `after`, `dist`, and `result` columns giving the values for each node reached from the current node. The `result` column will contain the result of the mapping of each node in a list.

Instead of spelling out all of these in the function it is possible to simply name the ones needed and use `...` to catch the rest.

Value

`map_bfs_back()` returns a list of the same length as the number of nodes in the graph, in the order matching the node order in the graph (that is, not in the order they are called). `map_bfs_back_*()` tries to coerce its result into a vector of the classes `logical` (map_bfs_back_lgl), `character` (map_bfs_back_chr), `integer` (map_bfs_back_int), or `double` (map_bfs_back_dbl). These functions will throw an error if they are unsuccesful, so they are type safe.

See Also

Other node map functions: [map_bfs()](), [map_dfs_back()](), [map_dfs()]()

Examples

```
# Collect values from children
create_tree(40, children = 3, directed = TRUE) %>%
  mutate(value = round(runif(40)*100)) %>%
  mutate(child_acc = map_bfs_back_dbl(node_is_root(), .f = function(node, path, ...) {
    if (nrow(path) == 0) .N()$value[node]
    else {
      sum(unlist(path$result[path$parent == node]))
    }
  }))
```

---

map_dfs   *Apply a function to nodes in the order of a depth first search*

Description

These functions allow you to map over the nodes in a graph, by first performing a depth first search on the graph and then mapping over each node in the order they are visited. The mapping function will have access to the result and search statistics for all the nodes between itself and the root in the search. To map over the nodes in the reverse direction use map_dfs_back().

Usage

```
map_dfs(root, mode = "out", unreachable = FALSE, .f, ...)

map_dfs_lgl(root, mode = "out", unreachable = FALSE, .f, ...)

map_dfs_chr(root, mode = "out", unreachable = FALSE, .f, ...)

map_dfs_int(root, mode = "out", unreachable = FALSE, .f, ...)

map_dfs_dbl(root, mode = "out", unreachable = FALSE, .f, ...)
```

Arguments

root	The node to start the search from
mode	How should edges be followed? 'out' only follows outbound edges, 'in' only follows inbound edges, and 'all' follows all edges. This parameter is ignored for undirected graphs.
unreachable	Should the search jump to an unvisited node if the search is completed without visiting all nodes.
.f	A function to map over all nodes. See Details
...	Additional parameters to pass to .f

Details

The function provided to .f will be called with the following arguments in addition to those supplied
through ...:

- graph: The full tbl_graph object
- node: The index of the node currently mapped over
- rank: The rank of the node in the search
- rank_out: The rank of the completion of the nodes subtree
- parent: The index of the node that led to the current node
- dist: The distance of the current node from the root
- path: A table containing node, rank, rank_out, parent, dist, and resultcolumns giving the values for each node
  column will contain the result of the mapping of each node in a list.

Instead of spelling out all of these in the function it is possible to simply name the ones needed and
use ... to catch the rest.

Value

map_dfs() returns a list of the same length as the number of nodes in the graph, in the order
matching the node order in the graph (that is, not in the order they are called). map_dfs_*() tries to
coerce its result into a vector of the classes logical (map_dfs_lgl), character (map_dfs_chr),
integer (map_dfs_int), or double (map_dfs_dbl). These functions will throw an error if they are
unsuccesful, so they are type safe.

See Also

Other node map functions: map_bfs_back(), map_bfs(), map_dfs_back()

Examples

```
# Add a random integer to the last value along a search
create_tree(40, children = 3, directed = TRUE) %>%
  mutate(child_acc = map_dfs_int(node_is_root(), .f = function(node, path, ...) {
    last_val <- if (nrow(path) == 0) 0L else tail(unlist(path$result), 1)
    last_val + sample(1:10, 1)
  }))
```

---

map_dfs_back   *Apply a function to nodes in the reverse order of a depth first search*

Description

These functions allow you to map over the nodes in a graph, by first performing a depth first search
on the graph and then mapping over each node in the reverse order they are visited. The mapping
function will have access to the result and search statistics for all the nodes following itself in the
search. To map over the nodes in the original direction use map_dfs().

Usage

```
map_dfs_back(root, mode = "out", unreachable = FALSE, .f, ...)

map_dfs_back_lgl(root, mode = "out", unreachable = FALSE, .f, ...)

map_dfs_back_chr(root, mode = "out", unreachable = FALSE, .f, ...)

map_dfs_back_int(root, mode = "out", unreachable = FALSE, .f, ...)

map_dfs_back_dbl(root, mode = "out", unreachable = FALSE, .f, ...)
```

Arguments

root	The node to start the search from
mode	How should edges be followed? `'out'` only follows outbound edges, `'in'` only follows inbound edges, and `'all'` follows all edges. This parameter is ignored for undirected graphs.
unreachable	Should the search jump to an unvisited node if the search is completed without visiting all nodes.
.f	A function to map over all nodes. See Details
...	Additional parameters to pass to .f

Details

The function provided to .f will be called with the following arguments in addition to those supplied through ...:

- graph: The full tbl_graph object
- node: The index of the node currently mapped over
- rank: The rank of the node in the search
- rank_out: The rank of the completion of the nodes subtree
- parent: The index of the node that led to the current node
- dist: The distance of the current node from the root
- path: A table containing node, rank, rank_out, parent, dist, and resultcolumns giving the values for each node column will contain the result of the mapping of each node in a list.

Instead of spelling out all of these in the function it is possible to simply name the ones needed and use ... to catch the rest.

Value

map_dfs_back() returns a list of the same length as the number of nodes in the graph, in the order matching the node order in the graph (that is, not in the order they are called). map_dfs_back_*() tries to coerce its result into a vector of the classes logical (map_dfs_back_lgl), character (map_dfs_back_chr), integer (map_dfs_back_int), or double (map_dfs_back_dbl). These functions will throw an error if they are unsuccesful, so they are type safe.

See Also

Other node map functions: map_bfs_back(), map_bfs(), map_dfs()

Examples

```
# Collect values from the 2 closest layers of children in a dfs search
create_tree(40, children = 3, directed = TRUE) %>%
  mutate(value = round(runif(40)*100)) %>%
  mutate(child_acc = map_dfs_back(node_is_root(), .f = function(node, path, dist, ...) {
    if (nrow(path) == 0) .N()$value[node]
    else {
      unlist(path$result[path$dist - dist <= 2])
    }
  }))
```

---

map_local   *Map a function over a graph representing the neighborhood of each*
                                   node

Description

This function extracts the neighborhood of each node as a graph and maps over each of these
neighborhood graphs. Conceptually it is similar to igraph::local_scan(), but it borrows the
type safe versions available in map_bfs() and map_dfs().

Usage

```
map_local(order = 1, mode = "all", mindist = 0, .f, ...)

map_local_lgl(order = 1, mode = "all", mindist = 0, .f, ...)

map_local_chr(order = 1, mode = "all", mindist = 0, .f, ...)

map_local_int(order = 1, mode = "all", mindist = 0, .f, ...)

map_local_dbl(order = 1, mode = "all", mindist = 0, .f, ...)
```

Arguments

order   Integer giving the order of the neighborhood.

mode   Character constant, it specifies how to use the direction of the edges if a directed
             graph is analyzed. For 'out' only the outgoing edges are followed, so all vertices
             reachable from the source vertex in at most order steps are counted. For '"in"'
             all vertices from which the source vertex is reachable in at most order steps are
             counted. '"all"' ignores the direction of the edges. This argument is ignored for
             undirected graphs.

mindist   The minimum distance to include the vertex in the result.

.f	A function to map over all nodes. See Details
...	Additional parameters to pass to .f

Details

The function provided to .f will be called with the following arguments in addition to those supplied through ...:

- neighborhood: The neighborhood graph of the node
- graph: The full tbl_graph object
- node: The index of the node currently mapped over

The neighborhood graph will contain an extra node attribute called .central_node, which will be TRUE for the node that the neighborhood is expanded from and FALSE for everything else.

Value

map_local() returns a list of the same length as the number of nodes in the graph, in the order matching the node order in the graph. map_local_*() tries to coerce its result into a vector of the classes logical (map_local_lgl), character (map_local_chr), integer (map_local_int), or double (map_local_dbl). These functions will throw an error if they are unsuccesful, so they are type safe.

Examples

```
# Smooth out values over a neighborhood
create_notable('meredith') %>%
  mutate(value = rpois(graph_order(), 5)) %>%
  mutate(value_smooth = map_local_dbl(order = 2, .f = function(neighborhood, ...) {
    mean(as_tibble(neighborhood, active = 'nodes')$value)
  }))
```

---

morph	*Create a temporary alternative representation of the graph to compute on*

Description

The morph/unmorph verbs are used to create temporary representations of the graph, such as e.g. its search tree or a subgraph. A morphed graph will accept any of the standard dplyr verbs, and changed to the data is automatically propagated to the original graph when unmorphing. Tidygraph comes with a range of [morphers](#), but is it also possible to supply your own. See Details for the requirement for custom morphers. The crystallise verb is used to extract the temporary graph representation into a tibble containing one separate graph per row and a name and graph column holding the name of each graph and the graph itself respectively. convert() is a shorthand for performing both morph and crystallise along with extracting a single tbl_graph (defaults to the first). For morphs were you know they only create a single graph, and you want to keep it, this is an easy way.

Usage

```
morph(.data, .f, ...)

unmorph(.data)

crystallise(.data)

crystallize(.data)

convert(.data, .f, ..., .select = 1, .clean = FALSE)
```

Arguments

`.data`	A `tbl_graph` or a `morphed_tbl_graph`
`.f`	A morphing function. See [morphers](#) for a list of provided one.
`...`	Arguments passed on to the morpher
`.select`	The graph to return during `convert()`. Either an index or the name as created during `crystallise()`.
`.clean`	Should references to the node and edge indexes in the original graph be removed when using `convert`

Details

It is only possible to change and add to node and edge data from a morphed state. Any filtering/removal of nodes and edges will not result in removal from the main graph. However, nodes and edges not present in the morphed state will be unaffected in the main graph when unmorphing (if new columns were added during the morhped state they will be filled with NA).

Morphing an already morhped graph will unmorph prior to applying the new morph.

During a morphed state, the mapping back to the original graph is stored in `.tidygraph_node_index` and `.tidygraph_edge_index` columns. These are accesible but protected, meaning that any changes to them with e.g. mutate will be ignored. Furthermore, if the morph results in the merging of nodes and/or edges the original data is stored in a `.data` column. This is protected as well.

When supplying your own morphers the morphing function should accept a `tbl_graph` as its first input. The provided graph will already have nodes and edges mapped with a `.tidygraph_node_index` and `.tidygraph_edge_index` column. The return value must be a `tbl_graph` or a list of `tbl_graphs` and these must contain either a `.tidygraph_node_index` column or a `.tidygraph_edge_index` column (or both). Note that it is possible for the morph to have the edges mapped back to the original nodes and vice versa (e.g. as with [to_linegraph](#)). In that case the edge data in the morphed graph(s) will contain a `.tidygraph_node_index` column and or the node data a `.tidygraph_edge_index` column. If the morphing results in the collapse of multiple columns or edges the index columns should be converted to list columns mapping the new node/edge back to all the nodes/edges it represents. Furthermore the original node/edge data should be collapsed to a list of tibbles, with the row order matching the order in the index column element.

Value

A `morphed_tbl_graph`

Examples

```
create_notable('meredith') %>%
  mutate(group = group_infomap()) %>%
  morph(to_contracted, group) %>%
  mutate(group_centrality = centrality_pagerank()) %>%
  unmorph()
```

---

morphers	*Functions to generate alternate representations of graphs*

Description

These functions are meant to be passed into morph() to create a temporary alternate representation of the input graph. They are thus not meant to be called directly. See below for detail of each morpher.

Usage

```
to_linegraph(graph)

to_subgraph(graph, ..., subset_by = NULL)

to_subcomponent(graph, node)

to_split(graph, ..., split_by = NULL)

to_components(graph, type = "weak")

to_complement(graph, loops = FALSE)

to_local_neighborhood(graph, node, order = 1, mode = "all")

to_dominator_tree(graph, root, mode = "out")

to_minimum_spanning_tree(graph, weights = NULL)

to_shortest_path(graph, from, to, mode = "out", weights = NULL)

to_bfs_tree(graph, root, mode = "out", unreachable = FALSE)

to_dfs_tree(graph, root, mode = "out", unreachable = FALSE)

to_simple(graph, remove_multiples = TRUE, remove_loops = TRUE)

to_contracted(graph, ..., simplify = TRUE)

to_unfolded_tree(graph, root, mode = "out")
```

```
to_directed(graph)

to_undirected(graph)

to_hierarchical_clusters(graph, method = "walktrap", weights = NULL, ...)
```

Arguments

`graph`	A `tbl_graph`
`...`	Arguments to pass on to [filter()], [group_by()], or the cluster algorithm (see [igraph::cluster_walktrap()], [igraph::cluster_leading_eigen()], and [igraph::cluster_edge_b]
`subset_by, split_by`	
	Whether to create subgraphs based on nodes or edges
`node`	The center of the neighborhood for `to_local_neighborhood()` and the node to that should be included in the component for `to_subcomponent()`
`type`	The type of component to split into. Either `'weak'` or `'strong'`
`loops`	Should loops be included. Defaults to `FALSE`
`order`	The radius of the neighborhood
`mode`	How should edges be followed? `'out'` only follows outbound edges, `'in'` only follows inbound edges, and `'all'` follows all edges. This parameter is ignored for undirected graphs.
`root`	The root of the tree
`weights`	Optional edge weights for the calculations
`from, to`	The start and end node of the path
`unreachable`	Should the search jump to a node in a new component when stuck.
`remove_multiples`	
	Should edges that run between the same nodes be reduced to one
`remove_loops`	Should edges that start and end at the same node be removed
`simplify`	Should edges in the contracted graph be simplified? Defaults to `TRUE`
`method`	The clustering method to use. Either `'walktrap'`, `'leading_eigen'`, or `'edge_betweenness'`

Value

A list of `tbl_graphs`

Functions

- `to_linegraph()`: Convert a graph to its line graph. When unmorphing node data will be merged back into the original edge data. Edge data will be ignored.

- `to_subgraph()`: Convert a graph to a single subgraph. `...` is evaluated in the same manner as `filter`. When unmorphing all data in the subgraph will get merged back.

- `to_subcomponent()`: Convert a graph to a single component containing the specified node

- `to_split()`: Convert a graph into a list of separate subgraphs. ... is evaluated in the same manner as `group_by`. When unmorphing all data in the subgraphs will get merged back, but in the case of `split_by = 'edges'` only the first instance of node data will be used (as the same node can be present in multiple subgraphs).

- `to_components()`: Split a graph into its separate components. When unmorphing all data in the subgraphs will get merged back.

- `to_complement()`: Convert a graph into its complement. When unmorphing only node data will get merged back.

- `to_local_neighborhood()`: Convert a graph into the local neighborhood around a single node. When unmorphing all data will be merged back.

- `to_dominator_tree()`: Convert a graph into its dominator tree based on a specific root. When unmorphing only node data will get merged back.

- `to_minimum_spanning_tree()`: Convert a graph into its minimum spanning tree/forest. When unmorphing all data will get merged back.

- `to_shortest_path()`: Limit a graph to the shortest path between two nodes. When unmorphing all data is merged back.

- `to_bfs_tree()`: Convert a graph into a breath-first search tree based on a specific root. When unmorphing only node data is merged back.

- `to_dfs_tree()`: Convert a graph into a depth-first search tree based on a specific root. When unmorphing only node data is merged back.

- `to_simple()`: Collapse parallel edges and remove loops in a graph. When unmorphing all data will get merged back

- `to_contracted()`: Combine multiple nodes into one. ... is evaluated in the same manner as `group_by`. When unmorphing all data will get merged back.

- `to_unfolded_tree()`: Unfold a graph to a tree or forest starting from multiple roots (or one), potentially duplicating nodes and edges.

- `to_directed()`: Make a graph directed in the direction given by from and to

- `to_undirected()`: Make a graph undirected

- `to_hierarchical_clusters()`: Convert a graph into a hierarchical clustering based on a grouping

Examples

```
# Compute only on a subgraph of every even node
create_notable('meredith') %>%
  morph(to_subgraph, seq_len(graph_order()) %% 2 == 0) %>%
  mutate(neighbour_count = centrality_degree()) %>%
  unmorph()
```

---

node_measures   *Querying node measures*

Description

These functions are a collection of node measures that do not really fall into the class of centrality measures. For lack of a better place they are collected under the node_* umbrella of functions.

Usage

```
node_eccentricity(mode = "out")

node_constraint(weights = NULL)

node_coreness(mode = "out")

node_diversity(weights)

node_bridging_score()

node_effective_network_size()

node_connectivity_impact()

node_closeness_impact()

node_fareness_impact()
```

Arguments

mode	The way edges should be followed in the case of directed graphs.
weights	The weights to use for each node during calculation

Value

A numeric vector of the same length as the number of nodes in the graph.

Functions

- node_eccentricity(): measure the maximum shortest path to all other nodes in the graph
- node_constraint(): measures Burts constraint of the node. See `igraph::constraint()`
- node_coreness(): measures the coreness of each node. See `igraph::coreness()`
- node_diversity(): measures the diversity of the node. See `igraph::diversity()`
- node_bridging_score(): measures Valente's Bridging measures for detecting structural bridges (influenceR)

- node_effective_network_size(): measures Burt's Effective Network Size indicating access to structural holes in the network (influenceR)

- node_connectivity_impact(): measures the impact on connectivity when removing the node (NetSwan)

- node_closeness_impact(): measures the impact on closeness when removing the node (NetSwan)

- node_fareness_impact(): measures the impact on fareness (distance between all node pairs) when removing the node (NetSwan)

Examples

```
# Calculate Burt's Constraint for each node
create_notable('meredith') %>%
  mutate(b_constraint = node_constraint())
```

---

node_rank   *Calculate node ranking*

Description

This set of functions tries to calculate a ranking of the nodes in a graph so that nodes sharing certain topological traits are in proximity in the resulting order. These functions are of great value when composing matrix layouts and arc diagrams but could concievably be used for other things as well.

Usage

```
node_rank_hclust(
  method = "average",
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_anneal(
  cool = 0.5,
  tmin = 1e-04,
  swap_to_inversion = 0.5,
  step_multiplier = 100,
  reps = 1,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)
```

```
node_rank_branch_bound(
  weighted_gradient = FALSE,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_traveller(
  method = "two_opt",
  ...,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_two(
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_mds(
  method = "cmdscale",
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_leafsort(
  method = "average",
  type = "OLO",
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_visual(
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)
```

```
node_rank_spectral(
  normalized = FALSE,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_spin_out(
  step = 25,
  nstart = 10,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_spin_in(
  step = 5,
  sigma = seq(20, 1, length.out = 10),
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_quadratic(
  criterion = "2SUM",
  reps = 1,
  step = 2 * graph_order(),
  step_multiplier = 1.1,
  temp_multiplier = 0.5,
  maxsteps = 50,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_genetic(
  ...,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_rank_dendser(
```

```
  ...,
  dist = "shortest",
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)
```

Arguments

method	The method to use. See *Functions* section for reference
dist	The algorithm to use for deriving a distance matrix from the graph. One of

- "shortest" (default): Use the shortest path between all nodes
- "euclidean": Calculate the L2 norm on the adjacency matrix of the graph
- "manhattan": Calculate the L1 norm on the adjacency matrix of the graph
- "maximum": Calculate the supremum norm on the adjacenecy matrix of the graph
- "canberra": Calculate a weighted manhattan distance on the adjacency matrix of the graph
- "binary": Calculate distance as the proportion of agreement between nodes based on the adjacency matrix of the graph

or a function that takes a tbl_graph and return a dist object with a size matching the order of the graph.

mode	Which edges should be included in the distance calculation. For distance measures based on the adjacency matrix, 'out' will use the matrix as is, 'in' will use the transpose, and 'all' will take the mean of the two. Defaults to 'out'. Ignored for undirected graphs.
weights	An edge variable to use as weight for the shortest path calculation if dist = 'shortest'
algorithm	The algorithm to use for the shortest path calculation if dist = 'shortest'
cool	cooling rate
tmin	minimum temperature
swap_to_inversion	
	Proportion of swaps in local neighborhood search
step_multiplier	
	Multiplication factor for number of iterations per temperature
reps	Number of repeats with random initialisation
weighted_gradient	
	minimize the weighted gradient measure? Defaults to FALSE
...	Arguments passed on to other algorithms. See *Functions* section for reference
type	The type of leaf reordering, either 'GW' to use the "GW" method or 'OLO' to use the "OLO" method (both in seriation)
normalized	Should the normalized laplacian of the similarity matrix be used?
step	The number iterations to run per initialisation

nstart	The number of random initialisations to perform
sigma	The variance around the diagonal to use for the weight matrix. Either a single number or a decreasing sequence.
criterion	The criterion to minimize. Either "LS" (Linear Seriation Problem), "2SUM" (2-Sum Problem), "BAR" (Banded Anti-Robinson form), or "Inertia" (Inertia criterion)
temp_multiplier	
	Temperature multiplication factor between 0 and 1
maxsteps	The upper bound of iterations

Value

An integer vector giving the position of each node in the ranking

Functions

- node_rank_hclust(): Use hierarchical clustering to rank nodes (see stats::hclust() for allowed methods)

- node_rank_anneal(): Use simulated annealing based on the "ARSA" method in seriation

- node_rank_branch_bound(): Use branch and bounds strategy to minimize the gradient measure (only feasable for small graphs). Will use "BBURCG" or "BBWRCG" in seriation dependent on the weighted_gradient argument

- node_rank_traveller(): Minimize hamiltonian path length using a travelling salesperson solver. See the the solve_TSP function in TSP for an overview of possible arguments

- node_rank_two(): Use Rank-two ellipse seriation to rank the nodes. Uses "R2E" method in seriation

- node_rank_mds(): Rank by multidimensional scaling onto one dimension. method = 'cmdscale' will use the classic scaling from stats, method = 'isoMDS' will use isoMDS from MASS, and method = 'sammon' will use sammon from MASS

- node_rank_leafsort(): Minimize hamiltonian path length by reordering leafs in a hierarchical clustering. Method refers to the clustering algorithm (either 'average', 'single', 'complete', or 'ward')

- node_rank_visual(): Use Prim's algorithm to find a minimum spanning tree giving the rank. Uses the "VAT" method in seriation

- node_rank_spectral(): Minimize the 2-sum problem using a relaxation approach. Uses the "Spectral" or "Spectral_norm" methods in seriation depending on the value of the norm argument

- node_rank_spin_out(): Sorts points into neighborhoods by pushing large distances away from the diagonal. Uses the "SPIN_STS" method in seriation

- node_rank_spin_in(): Sorts points into neighborhoods by concentrating low distances around the diagonal. Uses the "SPIN_NH" method in seriation

- node_rank_quadratic(): Use quadratic assignment problem formulations to minimize criterions using simulated annealing. Uses the "QAP_LS", "QAP_2SUM", "QAP_BAR", or "QAP_Inertia" methods from seriation dependant on the criterion argument

- node_rank_genetic(): Optimizes different criteria based on a genetic algorithm. Uses the "GA" method from seriation. See register_GA for an overview of relevant arguments

- node_rank_dendser(): Optimizes different criteria based on heuristic dendrogram seriation. Uses the "DendSer" method from seriation. See register_DendSer for an overview of relevant arguments

Examples

```
graph <- create_notable('zachary') %>%
  mutate(rank = node_rank_hclust())
```

---

node_topology   *Node properties related to the graph topology*

Description

These functions calculate properties that are dependent on the overall topology of the graph.

Usage

```
node_dominator(root, mode = "out")

node_topo_order(mode = "out")
```

Arguments

| root | The node to start the dominator search from |
| mode | How should edges be followed. Either 'in' or 'out' |

Value

A vector of the same length as the number of nodes in the graph

Functions

- node_dominator(): Get the immediate dominator of each node. Wraps igraph::dominator_tree().

- node_topo_order(): Get the topological order of nodes in a DAG. Wraps igraph::topo_sort().

Examples

```
# Sort a graph based on its topological order
create_tree(10, 2) %>%
  arrange(sample(graph_order())) %>%
  mutate(old_ind = seq_len(graph_order())) %>%
  arrange(node_topo_order())
```

---

node_types   *Querying node types*

Description

These functions all lets the user query whether each node is of a certain type. All of the functions
returns a logical vector indicating whether the node is of the type in question. Do note that the types
are not mutually exclusive and that nodes can thus be of multiple types.

Usage

```
node_is_cut()

node_is_root()

node_is_leaf()

node_is_sink()

node_is_source()

node_is_isolated()

node_is_universal(mode = "out")

node_is_simplical(mode = "out")

node_is_center(mode = "out")

node_is_adjacent(to, mode = "all", include_to = TRUE)

node_is_keyplayer(k, p = 0, tol = 1e-04, maxsec = 120, roundsec = 30)
```

Arguments

mode	The way edges should be followed in the case of directed graphs.
to	The nodes to test for adjacency to
include_to	Should the nodes in to be marked as adjacent as well
k	The number of keyplayers to identify
p	The probability to accept a lesser state
tol	Optimisation tolerance, below which the optimisation will stop
maxsec	The total computation budget for the optimization, in seconds
roundsec	Number of seconds in between synchronizing workers' answer

Value

A logical vector of the same length as the number of nodes in the graph.

Functions

- `node_is_cut()`: is the node a cut node (articaultion node)
- `node_is_root()`: is the node a root in a tree
- `node_is_leaf()`: is the node a leaf in a tree
- `node_is_sink()`: does the node only have incomming edges
- `node_is_source()`: does the node only have outgoing edges
- `node_is_isolated()`: is the node unconnected
- `node_is_universal()`: is the node connected to all other nodes in the graph
- `node_is_simplical()`: are all the neighbors of the node connected
- `node_is_center()`: does the node have the minimal eccentricity in the graph
- `node_is_adjacent()`: is a node adjacent to any of the nodes given in `to`
- `node_is_keyplayer()`: Is a node part of the keyplayers in the graph (`influenceR`)

Examples

```
# Find the root and leafs in a tree
create_tree(40, 2) %>%
  mutate(root = node_is_root(), leaf = node_is_leaf())
```

---

  pair_measures   *Calculate node pair properties*

Description

This set of functions can be used for calculations that involve node pairs. If the calculateable measure is not symmetric the function will come in two flavours, differentiated with `_to/_from` suffix. The `*_to()` functions will take the provided node indexes as the target node (recycling if necessary). For the `*_from()` functions the provided nodes are taken as the source. As for the other wrappers provided, they are intended for use inside the `tidygraph` framework and it is thus not necessary to supply the graph being computed on as the context is known.

Usage

```
node_adhesion_to(nodes)

node_adhesion_from(nodes)

node_cohesion_to(nodes)

node_cohesion_from(nodes)
```

```
node_distance_to(nodes, mode = "out", weights = NULL, algorithm = "automatic")

node_distance_from(
  nodes,
  mode = "out",
  weights = NULL,
  algorithm = "automatic"
)

node_cocitation_with(nodes)

node_bibcoupling_with(nodes)

node_similarity_with(nodes, mode = "out", loops = FALSE, method = "jaccard")

node_max_flow_to(nodes, capacity = NULL)

node_max_flow_from(nodes, capacity = NULL)
```

Arguments

nodes	The other part of the node pair (the first part is the node defined by the row). Recycled if necessary.
mode	How should edges be followed? If `'all'` all edges are considered, if `'in'` only inbound edges are considered, and if `'out'` only outbound edges are considered
weights	The weights to use for calculation
algorithm	The distance algorithms to use. By default it will try to select the fastest suitable algorithm. Possible values are "automatic", "unweighted", "dijkstra", "bellman-ford", and "johnson"
loops	Should loop edges be considered
method	The similarity measure to calculate. Possible values are: "jaccard", "dice", and "invlogweighted"
capacity	The edge capacity to use

Value

A numeric vector of the same length as the number of nodes in the graph

Functions

- node_adhesion_to(): Calculate the adhesion to the specified node. Wraps igraph::edge_connectivity()
- node_adhesion_from(): Calculate the adhesion from the specified node. Wraps igraph::edge_connectivity()
- node_cohesion_to(): Calculate the cohesion to the specified node. Wraps igraph::vertex_connectivity()
- node_cohesion_from(): Calculate the cohesion from the specified node. Wraps igraph::vertex_connectivity()
- node_distance_to(): Calculate various distance metrics between node pairs. Wraps igraph::distances()

- node_distance_from(): Calculate various distance metrics between node pairs. Wraps igraph::distances()

- node_cocitation_with(): Calculate node pair cocitation count. Wraps igraph::cocitation()

- node_bibcoupling_with(): Calculate node pair bibliographic coupling. Wraps igraph::bibcoupling()

- node_similarity_with(): Calculate various node pair similarity measures. Wraps igraph::similarity()

- node_max_flow_to(): Calculate the maximum flow to a node. Wraps igraph::max_flow()

- node_max_flow_from(): Calculate the maximum flow from a node. Wraps igraph::max_flow()

Examples

```
# Calculate the distance to the center node
create_notable('meredith') %>%
  mutate(dist_to_center = node_distance_to(node_is_center()))
```

---

reroute   *Change terminal nodes of edges*

Description

The reroute verb lets you change the beginning and end node of edges by specifying the new indexes of the start and/or end node(s). Optionally only a subset of the edges can be rerouted using the subset argument, which should be an expression that are to be evaluated in the context of the edge data and should return an index compliant vector (either logical or integer).

Usage

```
reroute(.data, from = NULL, to = NULL, subset = NULL)
```

Arguments

.data	A tbl_graph or morphed_tbl_graph object. grouped_tbl_graph will be ungrouped prior to rerouting
from, to	The new indexes of the terminal nodes. If NULL nothing will be changed
subset	An expression evaluating to an indexing vector in the context of the edge data.

Value

An object of the same class as .data

Examples

```
# Switch direction of edges
create_notable('meredith') %>%
  activate(edges) %>%
  reroute(from = to, to = from)

# Using subset
create_notable('meredith') %>%
  activate(edges) %>%
  reroute(from = 1, subset = to > 10)
```

---

sampling_games	*Graph games based on direct sampling*

Description

This set of graph games creates graphs directly through sampling of different attributes, topologies, etc. The nature of their algorithm is described in detail at the linked igraph documentation.

Usage

```
play_degree(out_degree, in_degree = NULL, method = "simple")

play_dotprod(position, directed = TRUE)

play_fitness(m, out_fit, in_fit = NULL, loops = FALSE, multiple = FALSE)

play_fitness_power(
  n,
  m,
  out_exp,
  in_exp = -1,
  loops = FALSE,
  multiple = FALSE,
  correct = TRUE
)

play_erdos_renyi(n, p, m, directed = TRUE, loops = FALSE)

play_geometry(n, radius, torus = FALSE)
```

Arguments

`out_degree, in_degree`

        The degrees of each node in the graph

`method`   The algorithm to use for the generation. Either `'simple'`, `'vl'`, or `'simple.no.multiple'`

`position`   The latent position of each node by column.

directed	Should the resulting graph be directed
m	The number of edges in the graph
out_fit, in_fit	
	The fitness of each node
loops	Are loop edges allowed
multiple	Are multiple edges allowed
n	The number of nodes in the graph.
out_exp, in_exp	
	Power law exponent of degree distribution
correct	Use finite size correction
p	The probabilty of an edge occuring
radius	The radius within which vertices are connected
torus	Should the vertices be distributed on a torus instead of a plane

Value

A tbl_graph object

Functions

- `play_degree()`: Create graphs based on the given node degrees. See `igraph::sample_degseq()`

- `play_dotprod()`: Create graphs with link probability given by the dot product of the latent position of termintating nodes. See `igraph::sample_dot_product()`

- `play_fitness()`: Create graphs where edge probabilities are proportional to terminal node fitness scores. See `igraph::sample_fitness()`

- `play_fitness_power()`: Create graphs with an expected power-law degree distribution. See `igraph::sample_fitness_pl()`

- `play_erdos_renyi()`: Create graphs with a fixed edge probability or count. See `igraph::sample_gnp()` and `igraph::sample_gnm()`

- `play_geometry()`: Create graphs by positioning nodes on a plane or torus and connecting nearby ones. See `igraph::sample_grg()`

See Also

Other graph games: `component_games`, `evolution_games`, `type_games`

Examples

```
plot(play_erdos_renyi(20, 0.3))
```

---

search_graph   *Search a graph with depth first and breath first*

Description

These functions wraps the `igraph::bfs()` and `igraph::dfs()` functions to provide a consistent return value that can be used in `dplyr::mutate()` calls. Each function returns an integer vector with values matching the order of the nodes in the graph.

Usage

```
bfs_rank(root, mode = "out", unreachable = FALSE)

bfs_parent(root, mode = "out", unreachable = FALSE)

bfs_before(root, mode = "out", unreachable = FALSE)

bfs_after(root, mode = "out", unreachable = FALSE)

bfs_dist(root, mode = "out", unreachable = FALSE)

dfs_rank(root, mode = "out", unreachable = FALSE)

dfs_rank_out(root, mode = "out", unreachable = FALSE)

dfs_parent(root, mode = "out", unreachable = FALSE)

dfs_dist(root, mode = "out", unreachable = FALSE)
```

Arguments

root	The node to start the search from
mode	How edges are followed in the search if the graph is directed. `"out"` only follows outbound edges, `"in"` only follows inbound edges, and `"all"` or `"total"` follows all edges. This is ignored for undirected graphs.
unreachable	Should the search jump to a new component if the search is terminated without all nodes being visited? Default to `FALSE` (only reach connected nodes).

Value

An integer vector, the nature of which is determined by the function.

Functions

- `bfs_rank()`: Get the succession in which the nodes are visited in a breath first search
- `bfs_parent()`: Get the nodes from which each node is visited in a breath first search

- bfs_before(): Get the node that was visited before each node in a breath first search
- bfs_after(): Get the node that was visited after each node in a breath first search
- bfs_dist(): Get the number of nodes between the root and each node in a breath first search
- dfs_rank(): Get the succession in which the nodes are visited in a depth first search
- dfs_rank_out(): Get the succession in which each nodes subtree is completed in a depth first search
- dfs_parent(): Get the nodes from which each node is visited in a depth first search
- dfs_dist(): Get the number of nodes between the root and each node in a depth first search

Examples

```
# Get the depth of each node in a tree
create_tree(10, 2) %>%
  activate(nodes) %>%
  mutate(depth = bfs_dist(root = 1))

# Reorder nodes based on a depth first search from node 3
create_notable('franklin') %>%
  activate(nodes) %>%
  mutate(order = dfs_rank(root = 3)) %>%
  arrange(order)
```

---

type_games   *Graph games based on different node types*

Description

This set of games are build around different types of nodes and simulating their interaction. The nature of their algorithm is described in detail at the linked igraph documentation.

Usage

```
play_preference(
  n,
  n_types,
  p_type = rep(1, n_types),
  p_pref = matrix(1, n_types, n_types),
  fixed = FALSE,
  directed = TRUE,
  loops = FALSE
)

play_preference_asym(
  n,
  n_types,
```

```
    p_type = matrix(1, n_types, n_types),
    p_pref = matrix(1, n_types, n_types),
    loops = FALSE
)

play_bipartite(n1, n2, p, m, directed = TRUE, mode = "out")

play_traits(
    n,
    n_types,
    growth = 1,
    p_type = rep(1, n_types),
    p_pref = matrix(1, n_types, n_types),
    callaway = TRUE,
    directed = TRUE
)

play_citation_type(
    n,
    growth,
    types = rep(0, n),
    p_pref = rep(1, length(unique(types))),
    directed = TRUE
)
```

Arguments

n, n1, n2	The number of nodes in the graph. For bipartite graphs n1 and n2 specifies the number of nodes of each type.
n_types	The number of different node types in the graph
p_type	The probability that a node will be the given type. Either a vector or a matrix, depending on the game
p_pref	The probability that an edge will be made to a type. Either a vector or a matrix, depending on the game
fixed	Should n_types be understood as a fixed number of nodes for each type rather than as a probability
directed	Should the resulting graph be directed
loops	Are loop edges allowed
p	The probabilty of an edge occuring
m	The number of edges in the graph
mode	The flow direction of edges
growth	The number of edges added at each iteration
callaway	Use the callaway version of the trait based game
types	The type of each node in the graph, enumerated from 0

Value

A tbl_graph object

Functions

- `play_preference()`: Create graphs by linking nodes of different types based on a defined probability. See `igraph::sample_pref()`

- `play_preference_asym()`: Create graphs by linking nodes of different types based on an asymmetric probability. See `igraph::sample_asym_pref()`

- `play_bipartite()`: Create bipartite graphs of fixed size and edge count or probability. See `igraph::sample_bipartite()`

- `play_traits()`: Create graphs by evolving a graph with type based edge probabilities. See `igraph::sample_traits()` and `igraph::sample_traits_callaway()`

- `play_citation_type()`: Create citation graphs by evolving with type based linking probability. See `igraph::sample_cit_types()` and `igraph::sample_cit_cit_types()`

See Also

Other graph games: `component_games`, `evolution_games`, `sampling_games`

Examples

```
plot(play_bipartite(20, 30, 0.4))
```

---

with_graph   *Evaluate a tidygraph algorithm in the context of a graph*

Description

All tidygraph algorithms are meant to be called inside tidygraph verbs such as `mutate()`, where the graph that is currently being worked on is known and thus not needed as an argument to the function. In the off chance that you want to use an algorithm outside of the tidygraph framework you can use `with_graph()` to set the graph context temporarily while the algorithm is being evaluated.

Usage

```
with_graph(graph, expr)
```

Arguments

graph	The `tbl_graph` to use as context
expr	The expression to evaluate

Value

The value of expr

Examples

```
gr <- play_erdos_renyi(10, 0.3)

with_graph(gr, centrality_degree())
```

Index